



SPIN code Note: SetAsReversed(RightWheel)

Note 1:

To run wheels first instead of Caster first, reverse the blue and yellow wires on the motors and change the SPIN code to: SetAsReversed(LeftWheel)

Note 2:

In some cases the HB-25's ignore good pulses and will not move at all.
The work around to this is to delay power to the HB-25's until after the Propeller powers up

Grue Robotics		
MPC Rool Test Details		
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