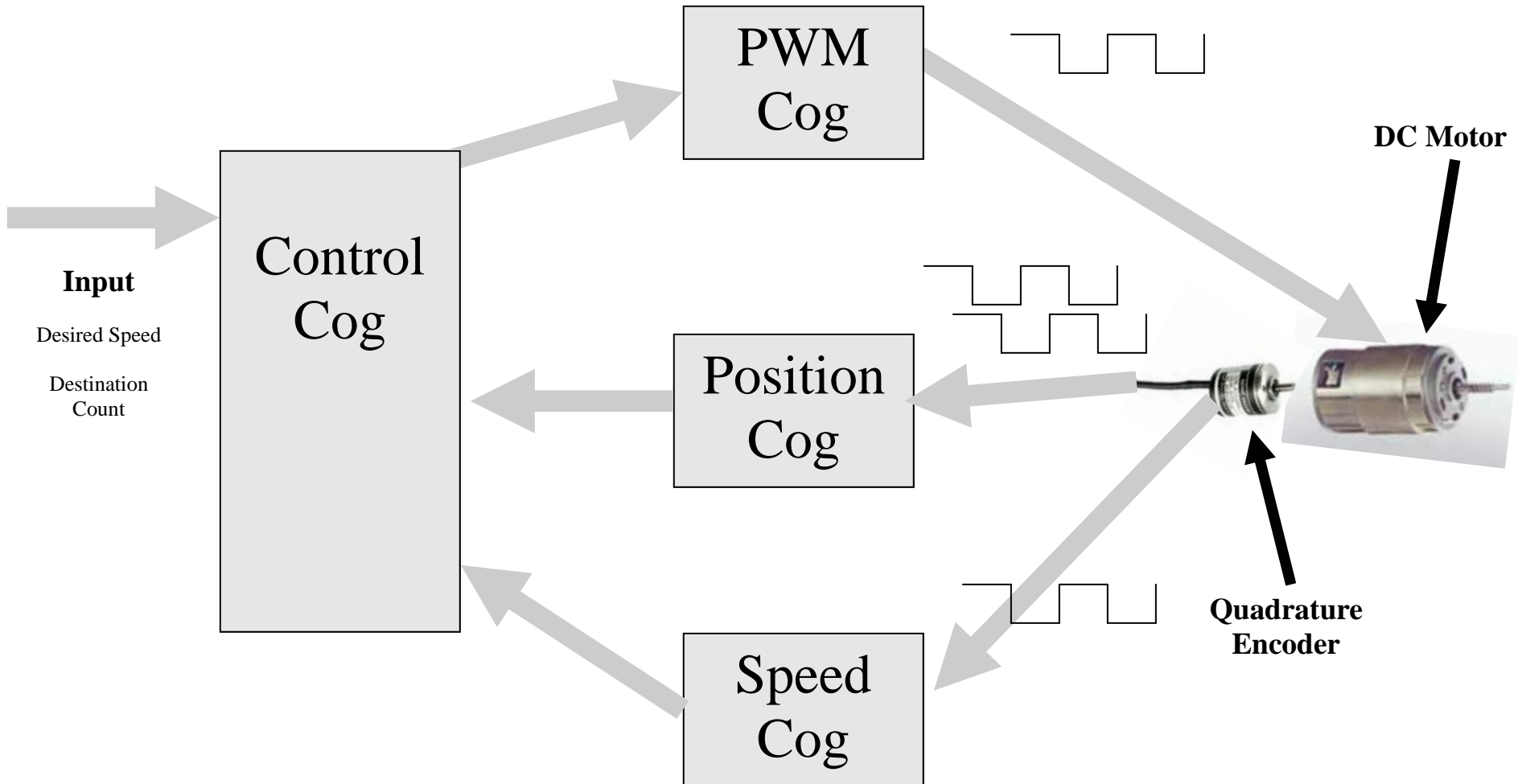
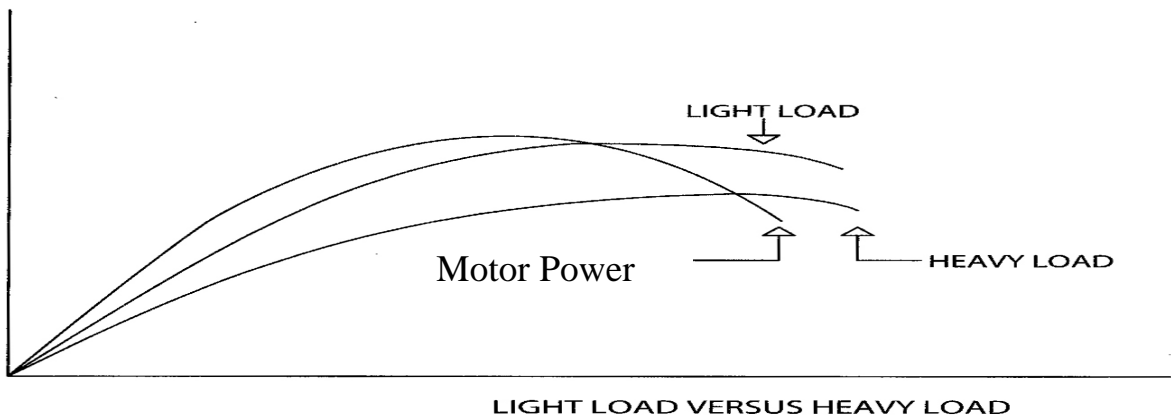
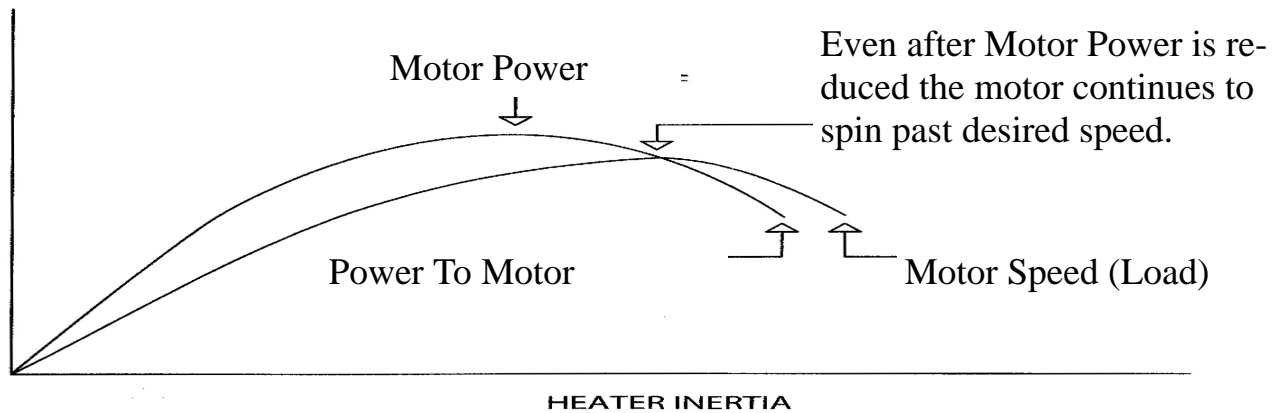


DC Motor Control



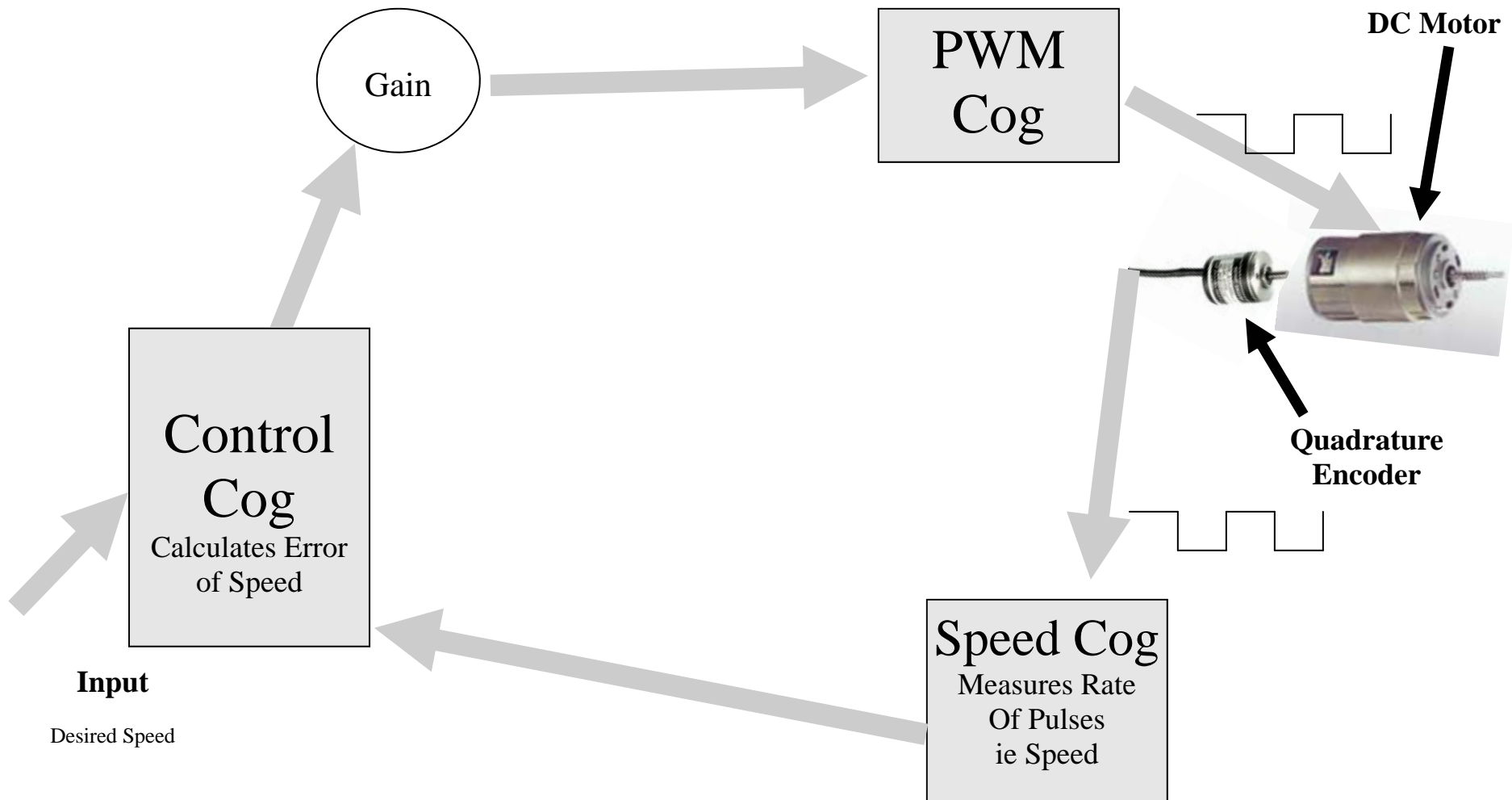
Proportional w Inertia DC Motor Control

To maintain constant speed



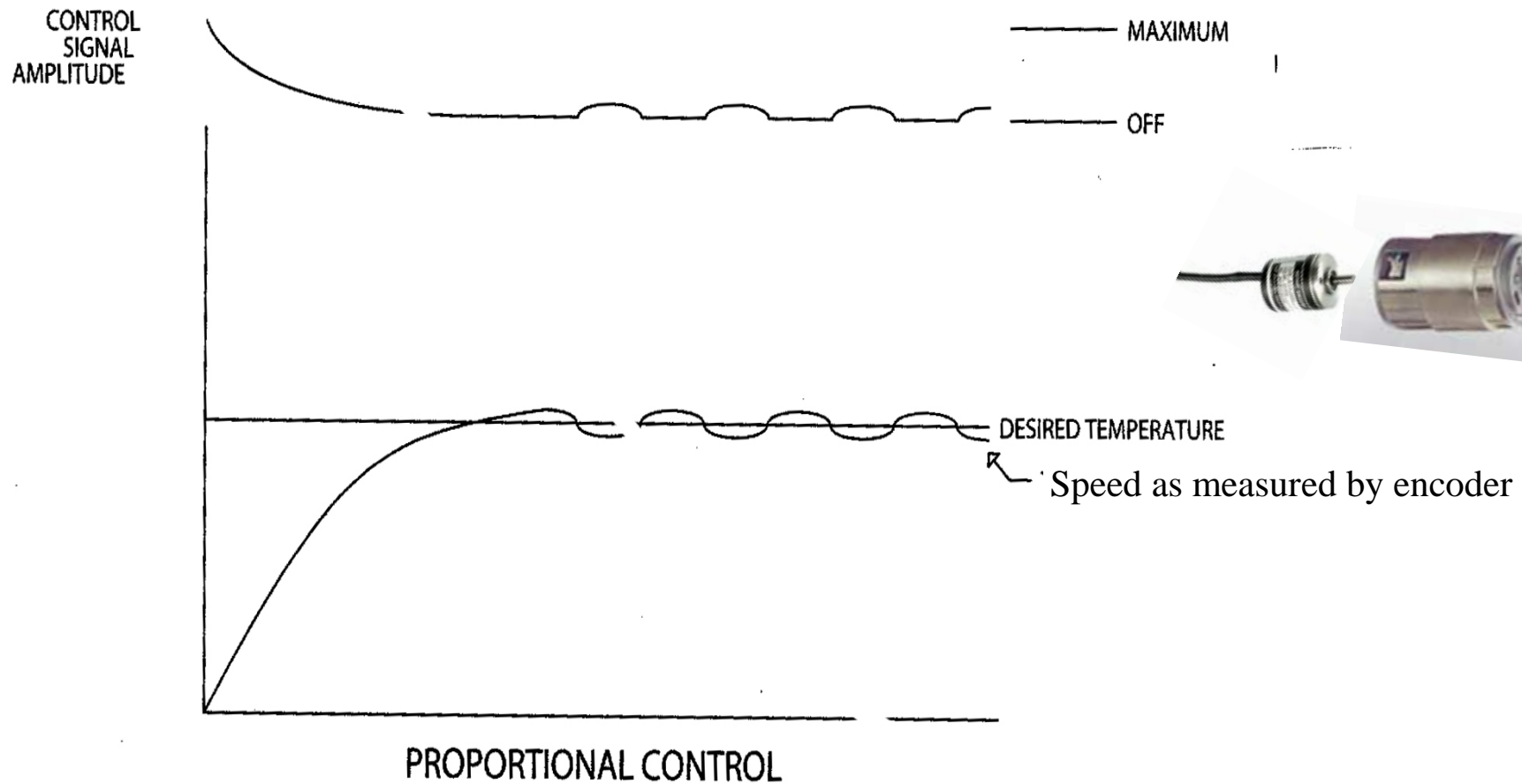
Proportional DC Motor Control

To maintain constant speed



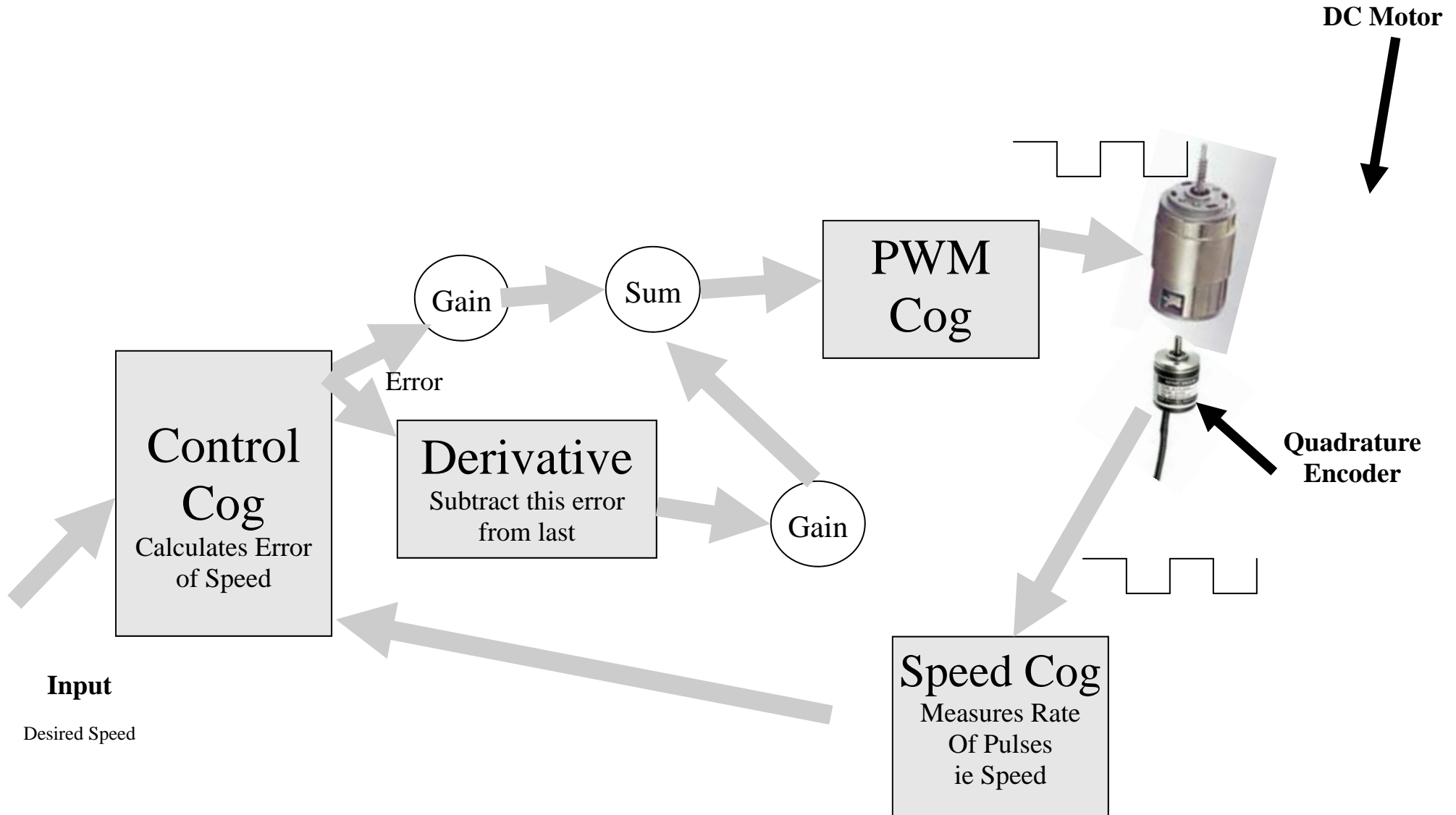
Proportional DC Motor Control

To maintain constant speed



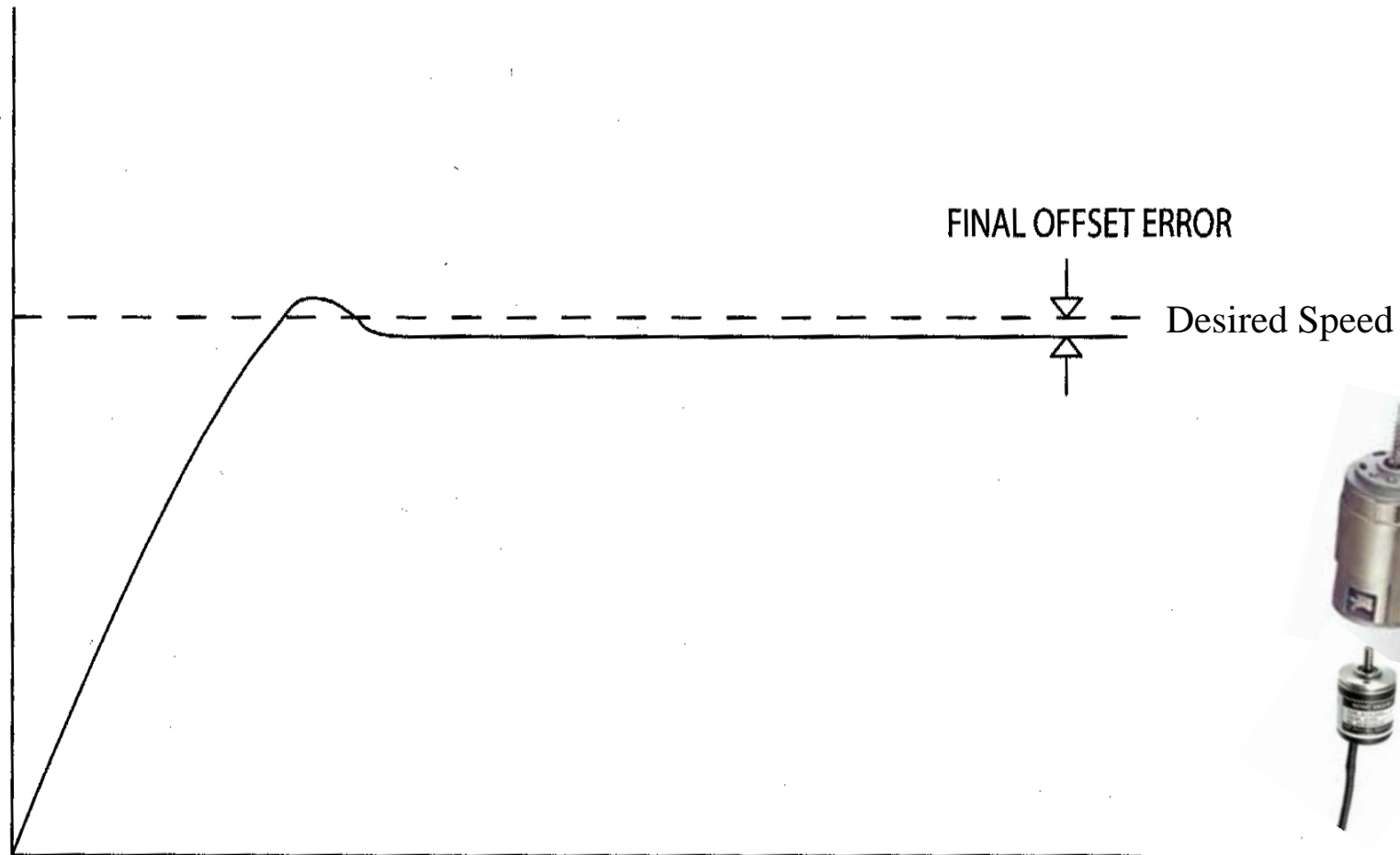
Proportional Derivative DC Motor Control

To maintain constant speed



Proportional Derivative DC Motor Control

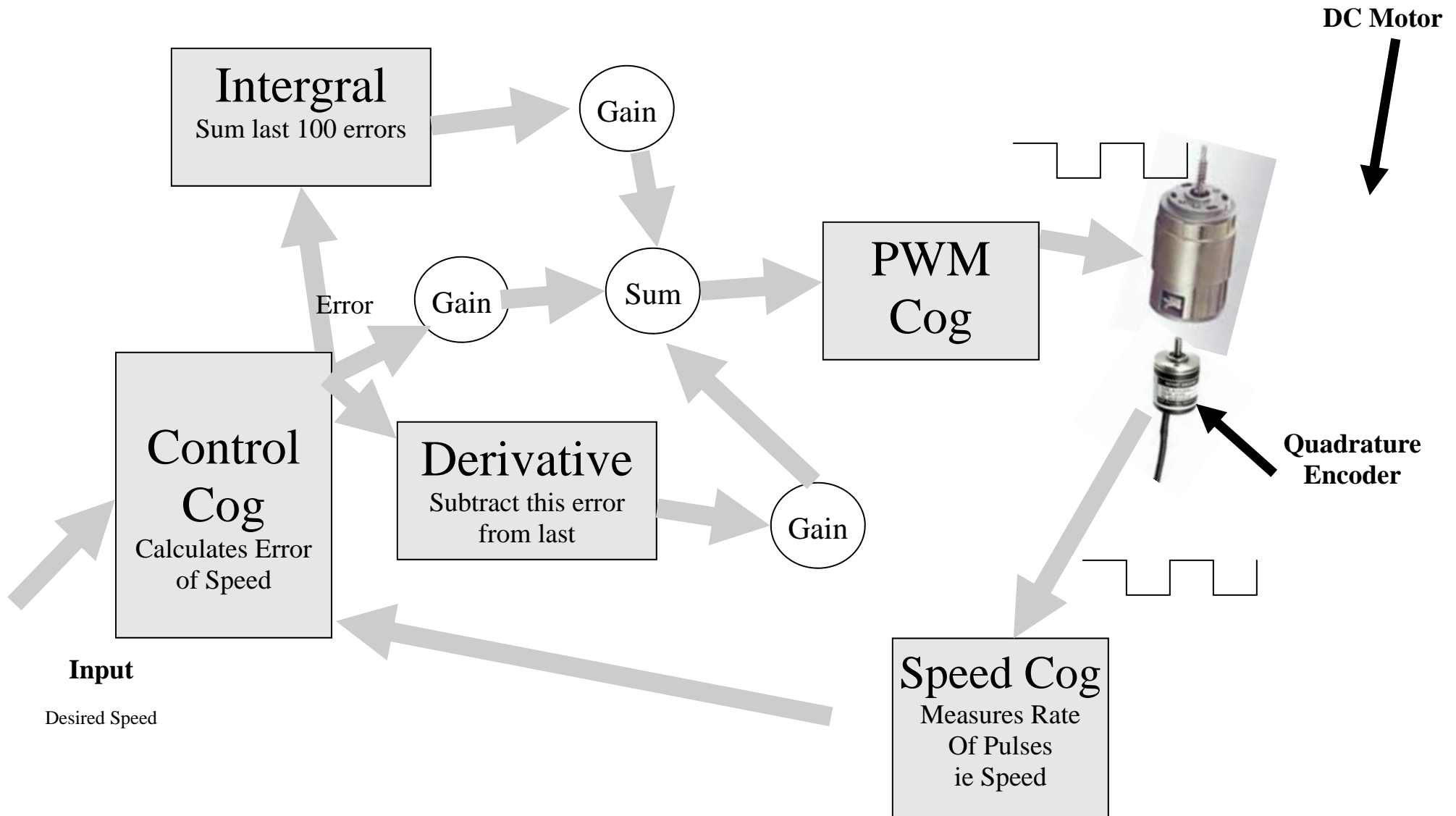
To maintain constant speed



Proportional Integral Derivative (PID)

DC Motor Control

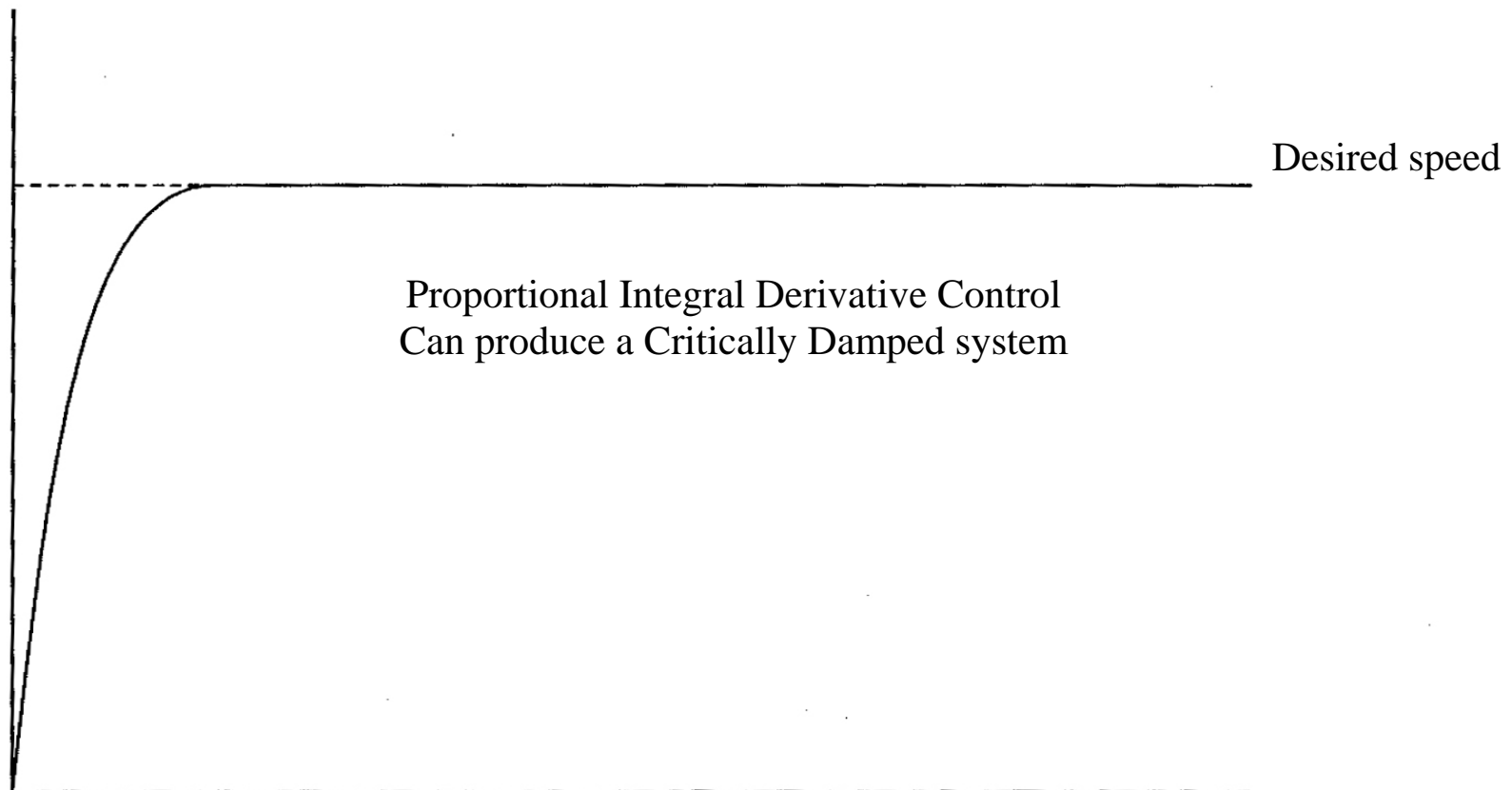
To maintain constant speed

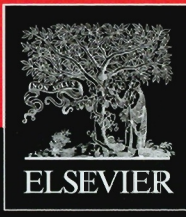


Proportional Integral Derivative (PID)

DC Motor Control

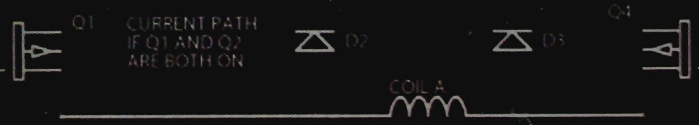
To maintain constant speed





EMBEDDED TECHNOLOGY™

SERIES



Analog Interfacing to Embedded Microprocessors

Real World Design

Second Edition

Stuart R. Ball, P.E.

