In the program we name the IO pins like this:

PWMH1 PIN 4

PWMH2 PIN 2

PWMH3 PIN 3

PWMH4 PIN 5

And we write the part program like this:

PWM 4, 50, 10

PWM 2, 50, 10

PWM 3, 50, 10

PWM 5, 5 0, 10

 **Pin#**

(PIN4/PIN2/PIN3/PIN5)

**Capacitor**

**Vss**

10kΩ

The circuit we connect like this :

**Motor driver green line**

[External DC power supply for speed setting anode (0 to 5VDC)]