



Standard type





Slight motion

detection type

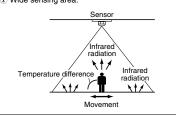
Spot type

10 m detection type

What is passive infrared type?

This sensor detects changes in infrared radiation which occur when there is movement by a person (or object) which is different in temperature from the surroundings.

- As this sensor detects temperature differences, it is well suited to detecting the motion of people by their body temperature.
- Wide sensing area.



RoHS Directive compatibility information http://www.mew.co.jp/ac/e/environment/

FEATURES

1. The world s smallest* with a built-in amplifier

Extremely compact. Ideal for use in miniaturized devices. (*Based on our investigation as of November, 2006)

MOTION SENSOR (PASSIVE INFRARED TYPE)

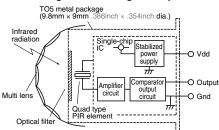
2. Dual lens colors (white and black) are available

With an ultrasmall design and dual lens colors (white and black), it is inconspicuous, allowing the user to select either white or black to match the equipment color. This provides greater flexibility in equipment design.

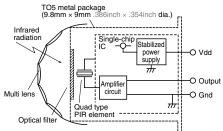
3. Both digital output and analog output (with adjustable sensitivity) are available.

4. Built-in amplifier for easy use Has a built-in amplifier, and can be connected directly to a microcomputer.

Block diagram of the digital output circuit



• Block diagram of the analog output circuit



5. Detects even slight motion of a person

With our sensor, even slight motions made by people will be detected easily. • Fine motion detection capability within

approximately 2 meters of sensor.

Standard type:

Detects movement of approximately 30cm 11.811inch.

MP MOTION SENSOR **'N a P i 0 n**'

Slight motion detection type: Detects movement of approximately

Detects movement of approximately 20cm 7.874inch.

6. Noise withstanding capability

Circuitry is contained in a TO5 metal package, providing at least twice the noise withstanding capability as conventional type.

Comparison example of noise withstanding capability

| U 1 | • |
|-------------------|---|
| | Distance at which motion sensor is not affected by cellular phone noise |
| Conventional type | Min. 1 to 2m 3.281 to 6.562ft |
| MP Motion Sensor | Min. 1 to 2cm .394 to .787inch |

7. A low current consumption type (46 A) has also been added to the lineup. A type that keeps current consumption to 46 μA (less than 30% compared to predecessor) is now available. Ideal for battery driven devices. *Digital output type only.

8. A more economically priced digital output type (ST type) has been launched.

APPLICATIONS

1. Home appliances

Useful for saving energy in air conditioner, television, personal computer, or ventilator and air purifier **2. Amusement machine market** Useful for saving energy and for

automated guidance in theme parks and large video games

3. Equipment in service market

Useful for automated guidance, automated announcements and energy saving in vending machines, ATMs, etc. **4. Lighting market**

Automated on/off controls, etc. for lamps, desk lamps, indoor lights, halls, stairway lights, etc.

ORDERING INFORMATION

| Output | AMN | | | 1 | | |
|--|---|--|--|---|--|--|
| 2: Analog output 3: Digital output (ST type) | 4: Low current consumption (digital output) | | | | | |
| Detection performance 1: Standard detection type 2: Slight motion detection type | 3: Spot detection type 4: 10m detection type | | | | | |
| Feature 1: PC board mounting type | | | | | | |
| Operating voltage 1: 5V DC | 2: 3V DC | | | | | |
| Lens color 1: Black | 2: White | | | | | |

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PRODUCT TYPES

| 1. Digital | output |
|------------|--------|
|------------|--------|

| Rated operating | Detection n | artarmanaa | Ambient | | Dort No | Packing | g quantity | | |
|--|----------------------|-------------------------|------------------------------|-------------|----------|----------|------------|---|--|
| voltage | voltage | erformance | temperature | Lens color | Part No. | Inner | Outer | | |
| | | Ctandard | | Black | AMN31111 | | | | |
| | Standard detection | Standard | | White | AMN31112 | | | | |
| | type | Low current | | Black | AMN41121 | 50 pcs. | | | |
| | | consumption | | White | AMN41122 | | 1,000 pcs. | | |
| | | Standard | | Black | AMN32111 | | | | |
| | Slight motion | | -20 to +60°C -4 to +140°F | White | AMN32112 | | | | |
| 3 to 6 V DC | detection type | Low current consumption | | Black | AMN42121 | | | | |
| | | | | White | AMN42122 | | | | |
| 2.2 to 3 V DC (Low current consumption type) | | Standard | | Black | AMN33111 | | | | |
| | Cost detection type | | | White | AMN33112 | | | | |
| | Spot detection type | Spot detection type | Low current | Low current | Black | AMN43121 | | | |
| 10-11-11-11-11-11-11-11-11-11-11-11-11-1 | | consumption | | White | AMN43122 | | | | |
| | | ype Low current | | Black | AMN34111 | | | | |
| | 10 m data di su tara | | | White | AMN34112 | 1 | | | |
| | 10m detection type | | | Black | AMN44121 | 1 | | | |
| | | | | consumption | | White | AMN44122 | 1 | |

2. Analog output

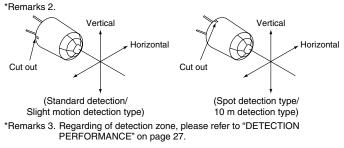
| Rated operating | Detection performance | Ambient | | Part No. | Packing quantity | | |
|-----------------|------------------------------|-------------------------------------|------------|----------|------------------|------------|--|
| voltage | Detection performance | temperature | Lens color | Part No. | Inner | Outer | |
| Chanda | Standard detection type | | Black | AMN21111 | | | |
| | Standard detection type | | White | AMN21112 | 50 pcs. | 1,000 pcs. | |
| | Slight motion detection type | −20 to +60°C −4 to +140°F | Black | AMN22111 | | | |
| 4.5 to 5.5 V DC | | | White | AMN22112 | | | |
| 4.5 10 5.5 V DC | Spot detection type | | Black | AMN23111 | 50 pcs. | | |
| | Spot detection type | | White | AMN23112 | | | |
| | 10m detection type | | Black | AMN24111 | _ | | |
| | 10m detection type | | White | AMN24112 | | | |

PERFORMANCE

1. Detection performance

| | Items | Standard detection type | Slight motion detection type | Spot detection type | 10m detection type | Conditions of objects to be detected |
|-----------------|-----------------------------|-------------------------|------------------------------|-----------------------|------------------------|---|
| Rated det | ection distance | 5m 16.404ft (Max.) | 2m 6.562ft (Max.) | 5m 16.404ft (Max.) | 10m 32.808ft (Max.) | Detectable difference in temperature between the target and background for the spot type is more than 4°C 39.2°F. Movement speed |
| | Horizontal *Remark 2 | 100° | 91° | 38° | 110° | Digital output type (ST type) Standard detection type/Spot detection type/ 10m detection type: 0.8 to 1.2 m/s Slight motion detection type: 0.5 m/s |
| Detection range | Vertical *Remark 2 | 82° | 91° | 22° | 93° | 2) Analog output and low current consumption types Standard detection type/Spot detection type/ 10m detection type: 0.5 to 1.5 m/s Slight motion detection type: 0.3 to 1.0 m/s |
| | Detection zone *Remark 3 | 64 zones | 104 zones | 24 zones | 80 zones | Detection object = human body (size is 700mm × 250mm 27.559inch × 9.843inch, but for the slight motion detection type the size is 200mm × 200mm 7.874inch × 7.874inch) |

*Remarks 1. Depending on the difference in temperature between the background and detection target and the speed at which the target moves, these sensors may be capable of detection beyond the detection distances stated above. Nevertheless, they should be used within the prescribed detection distances. For further details, refer to the detection range diagram on page 20.



| 2. Rating (Measuring condition: ambien | t temp. = $25^{\circ}C 77^{\circ}F$) (Common to All types |) |
|--|--|--|
| Items | Specified value | Remarks |
| Power supply voltage | -0.3 to 7 V DC | |
| Usable ambient temperature | −20 to 60°C −4 to +140°F | No freezing and condensing at low temperature. |
| Storage temperature | −20 to 70°C −4 to +158°F | |

3. Electrical characteristics (Measuring condition: ambient temp. = 25°C 77°F; operating voltage = 5V) (Common to All types) 1) Digital output

| Itomo | | Specified value | | ed value | Manager and time | | |
|--------------------------------------|-----------|-------------------------------|--------|---|------------------|-------------------------|--|
| | Items | | Symbol | Symbol Standard type Low current consumption ty | | Measured conditions | |
| Rated operating v | oltage | Minimum Typical Maximum | Vdd | 3.0 V DC | 2.2 V DC | | |
| Rated consumptic (Standby)*Remark | n current | Typical Maximum | Iw | 170 μΑ 300 μΑ | 46 μΑ 60 μΑ | lout = 0 | |
| Outrast | Current | Maximum | lout | 100 µA | 100 µA | Vout ≧ Vdd–0.5 | |
| Output (when detecting) | Voltage | Minimum Maximum | Vout | Vdd –0.5 — | Vdd0.5 | Open when not detecting | |
| Circuit stability tim | e | Typical Maximum | Twu | 7 s 30 s | 7 s 30 s | | |

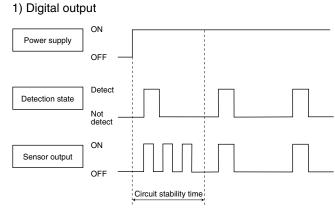
Remark: The current which is consumed during detection consists of the standby consumed current plus the output current.

2) Analog output

| Items | | Symbol Specified value | | Measured conditions |
|-------------------------------|-------------------------------|------------------------|--------------------------|--|
| Rated operating voltage | Minimum Maximum | Vdd | 4.5 V DC 5.5 V DC | |
| Rated consumption current | Typical Maximum | lw | 0.17 mA 0.3 mA | lout = 0 |
| Output current | Maximum | lout | 50 µA | |
| Output voltage | Minimum Typical Maximum | Vout | 0 V 2.5 V Vdd | |
| Output offset average voltage | Minimum Typical Maximum | Voff | 2.3 V 2.5 V 2.7 V | Steady-state output voltage when not detecting |
| Steady-state noise | Typical Maximum | Vn | 155 m Vp-p 300 m Vp-p | |
| Circuit stability time | Maximum | Twu | 45 s | |

Note: To set to the same detection performance as the digital type, set the output voltage to the offset voltage (2.5V) ±0.45V (i.e. 2.95V or more and 2.05V or less).

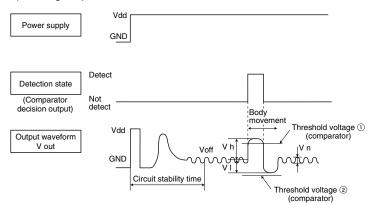
[Timing chart]



Remark[.]

Circuit stability time: 30s max. While the circuitry is stabilizing after the power is turned on, the sensor output is not fixed in the "on" state or "off" state. This is true regardless of whether or not the sensor has detected anything.

2) Analog output



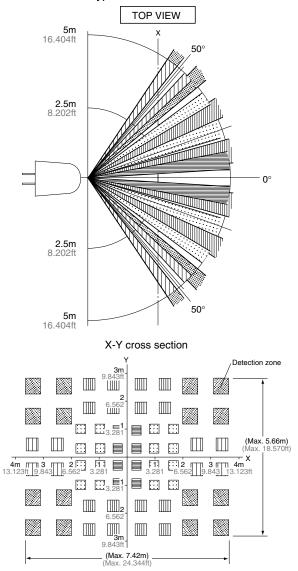
Remark: Circuit stability time: 45s max.

While the circuitry is stabilizing after the power is turned on, the sensor output is not fixed in the 'on' state or 'off' state. This is true regardless of whether or not the sensor has detected anything.

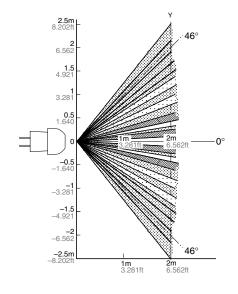
DETECTION PERFORMANCE

MP Motion Sensor (AMN2, 3, 4)

1. Standard detection type



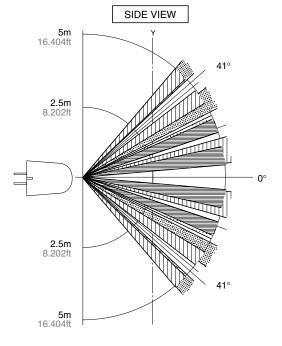
2. Slight motion detection type



Remarks:

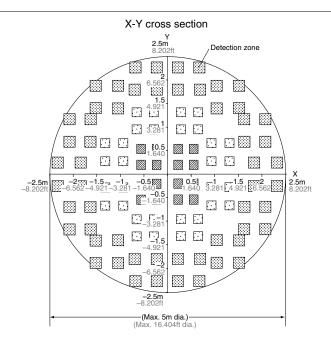
1. The X-Y cross-sectional diagram shows the detection area.

The differences in the detection zone patterns are indicative of the projections of the 26 lenses with single focal point and with three optical axes. An object whose



Remarks:

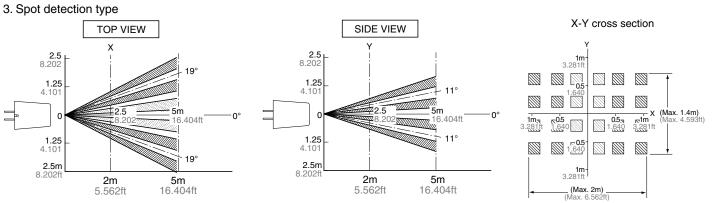
- 1. The X-Y cross-sectional diagram shows the detection area.
- 2. The differences in the detection zone patterns are indicative of the projections of the 16 lenses with single focal point and with five optical axes. An object whose temperature differs from the background temperature and which crosses inside the detection zone will be detected.



temperature differs from the background temperature and which crosses inside the detection zone will be detected.

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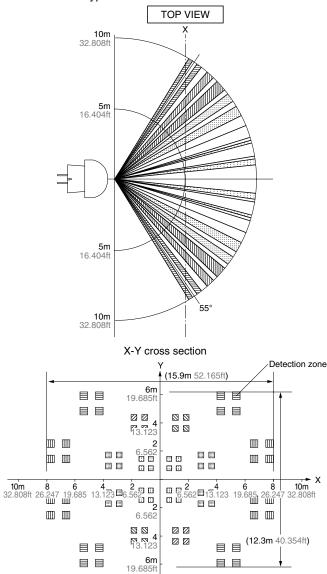
MP Motion Sensor (AMN2, 3, 4)



Remarks: 1. The X-Y cross-sectional diagram shows the detection area.

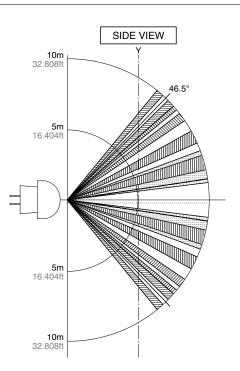
2. The differences in the detection zone patterns are indicative of the projections of the 6 lenses with single focal point and with two optical axes. An object whose temperature differs from the background temperature and which crosses inside the detection zone will be detected.

4.10m detection type



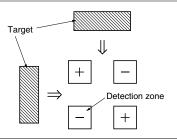
5. Notes regarding the detection zone

The detection zone has the polarity shown in the diagram on the right. When targets enter both the + and - zones with the same timing, the signals are cancelled each other, thus in this case there is a possibility that the object cannot be detected at the maximum specified detection distance.



Remarks:

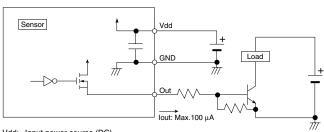
- 1. The X-Y cross-sectional diagram shows the detection area.
- 2. The differences in the detection zone patterns are indicative of the projections of the 20 lenses with single focal point and with five optical axes. An object whose temperature differs from the background temperature and which crosses inside the detection zone will be detected.



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HOW TO USE

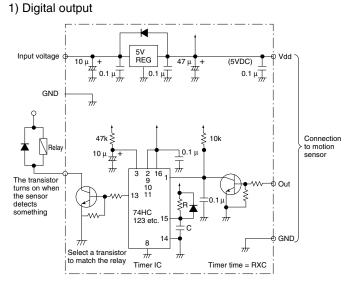
- 1. Wiring diagram
- 1) Digital output



Vdd: Input power source (DC) GND: GND

Out: Output (Comparator)

2. Timer circuit example



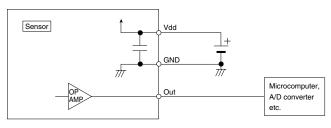
Note: This is the reference circuit which drives the MP motion sensor. Install a noise filter for applications requiring enhanced detection reliability and noise withstanding capability.

Differences in the specifications of electronic components to which the units are connected sometimes affect their correct operation; please check the units' performance and reliability for each application.

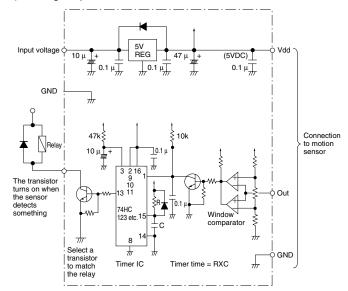
3. Installation

Install the sensor so that people will be entering from the X or Y direction shown below. If persons approch the sensor from the Z direction, detection distance will be shortened.

2) Analog output

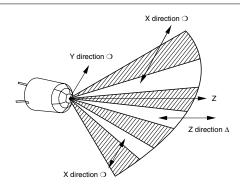


2) Analog output



Note: This circuit is a sample of a drive circuit for the MP Motion Sensor. Its noise resistance and long-term reliability are not considered or investigated. To improve the detection reliability and noise resistance of the circuit, consider adding a noise filter.

Matsushita Electric Works, Ltd. accepts no responsibility for damages resulting from the use of this circuit.

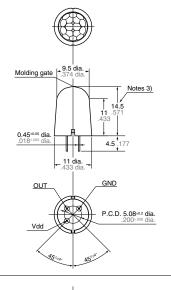


MP Motion Sensor (AMN2, 3, 4)

DIMENSIONS

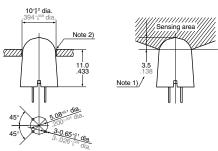
1. Standard detection type





Recommended PC board pattern

mm inch General tolerance $\pm 0.5 \pm .020$

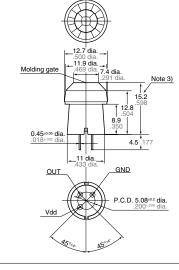


Notes: 1. In order to ensure proper detection, install it with the lens exposed at least 3.5mm .138inch.

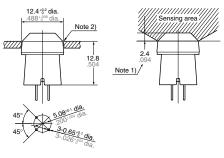
- 2. As for panel mounting hole, tapering or making a
- large size hole should be done.
- 3. The height dimension does not include the remaining molding gate.

2. Slight motion detection type





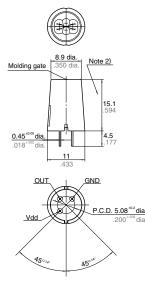
Recommended PC board pattern



Notes: 1. In order to ensure proper detection, install it with the

- lens exposed at least 2.4mm .094inch. 2. As for panel mounting hole, tapering or making a large size hole should be done.
- 3. The height dimension does not include the remaining molding gate.

3. Spot detection type



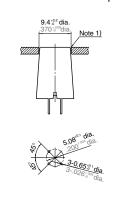
Notes: 1. As for panel mounting hole, tapering or making a large

2. The height dimension does not include the remaining

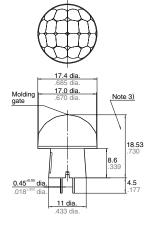
size hole should be done.

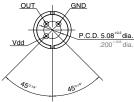
molding gate.

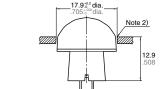
Recommended PC board pattern



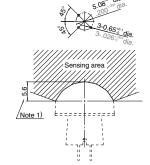
4. 10m detection type







Recommended PC board pattern



Notes:

- 1. In order to ensure proper detection, install it with the lens exposed at least 5.6mm .220inch.
- 2. As for panel mounting hole, tapering or
- making a large size hole should be done. 3. The height dimension does not include the remaining molding gate.

NOTES

1. Checkpoints relating to principle of operation

MP motion sensors are passive infrared sensors which detect changes in the infrared rays. They may fail to detect successfully if a heat source other than a human being is detected or if there are no temperature changes in or movement of a heat source. Care must generally be taken in the following cases. The performance and reliability of the sensors must be checked out under conditions of actual use.

<1> Cases where a heat source other than a human being is detected.

1) When a small animal enters the

detection range. 2) When the sensor is directly exposed to sunlight, a vehicle's headlights, an incandescent light or some other source

of far infrared rays. 3) When the temperature inside the detection range has changed suddenly due to the entry of cold or warm air from an air-conditioning or heating unit, water vapor from a humidifier, etc.

<2> Cases where it is difficult to detect the heat source

1) When an object made of glass, acrylic or other subject which far infrared rays have difficulty passing through is located between the sensor and what is to be detected.

2) When the heat source inside the detection range hardly moves or when it moves at high speed; for details on the movement speed, refer to the section on the performance ratings.

2. When the detection area becomes larger

When the difference between the ambient temperature and body temperature is large (more than 20°C 68°F), detection may occur in isolated areas outside the specified detection range.

3. Other handling cautions

 Be careful not to allow dust or dirt to accumulate on the lens as this will adversely affect the detection sensitivity.
 The lens is made of a soft material (polyethylene).

Avoid applying a load or impact since this will deform or scratch the lens, making proper operation impossible and causing a deterioration in its performance. 3) The sensor may be damaged if it is exposed to static with a voltage exceeding $\pm 200V$. Therefore, do not touch its terminals directly, and exercise adequate care in the handling of the sensor.

4) When the leads are to be soldered, solder them by hand for less than 3 seconds at a temperature of less than 350°C 662°F at the tip of the soldering iron. Avoid using a solder bath since this will causing a deterioration in the sensor's performance.

5) Do not attempt to clean the sensor. Cleaning fluid may enter inside the lens area causing a deterioration in performance.

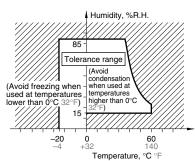
6) When using the sensors with cables, it is recommended that cables which are shielded and as short as possible be used in order to safeguard against the effects of noise.

4. Ambient operating conditions

1) Temperature: Refer to the absolute maximum ratings for the temperature of each individual sensor.

2) Humidity: 15% to 85% RH (No freezing nor condensation at low temperature)
3) Atmospheric pressure: 86 to 106 kPa
4) Because the humidity range differs depending on the ambient temperature, the humidity range indicated below should be used. Continuous operation of the switch is possible within this range, but continuous use near the limit of the range should be avoided. This humidity range does not guarantee permanent performance.

<MP Motion Sensor>



In general, degradation of electronic devices accelerates when they are operated under conditions of high temperature or high humidity. Before use, confirm the reliability of the sensors under the expected operating conditions. 5) When the sensor (especially for ST type) is used in noisy environments, connect a capacitor (approx. 1μ F) across its power input terminals and sensor output terminals.

6) The sensors do not have a water-proof or dust-proof construction. Depending on the ambient operating conditions, some means of providing protection from water and dust and preventing the formation of ice and condensation must be provided prior to using the sensors. If a sensor is used with a cover installed, the initial detection performance specifications may not be able to be met. Confirm the operation under the actual operating conditions.

7) Take care to avoid exposing the sensors to heat, vibration or impact since malfunctioning may result.

5. Concerning external surge voltages

Since the internal circuitry may be destroyed if an external surge voltages is supplied, provide an element which will absorb the surges. The levels of the voltage surges which the sensor can withstand is given below.

MP motion sensors: Within the supply voltage given in the absolute maximum ratings.

6. Concerning power supplysuperimposed noise

Use a regulated power supply as the power supply. Otherwise, power supplysuperimposed noise may cause the sensors to malfunction. The levels of noise which the sensor can withstand is given below.

MP motion sensors: ± 20 V (50ns, 1 μs wide square waves)

7. Drop damage

If the sensor is dropped, damage can occur resulting in incorrect operation. If dropped, be sure to do a visual check of the exterior for noticeable damage and check the operation characteristics for faulty operation.

8. Concerning the circuit sides Since the circuit sides given in this catalog are not protected in terms of circuit design, check out the performance and reliability of the circuits prior to using the sensors.