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Sigma Delta Driver
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 History:
                                                      Version 1 - 04-09-2013)
                                                                                                             initial concept
Schematic:
                             10k
                               Drive Pin
                               $ 10k
                                                         → A (see text)
Feedback Pin
                             .01uF
                             Vss
Theory:
 Note: A key feature with this sigma-delta ADC is that the drive pin is set to an input shortly after the sample period. A Typical configuration usually has the drive pin always set as an output and driven either HIGH or LOW and the external analog input is connected to a node I have labeled as "A". That method creates more of a voltage overshoot as the ADC tries to search introducing unnecessary noise. By placing the analog input on the drive pin, the analog signal is blocked from the feedback pin during the sample period. When the drive pin becomes an input the analog signal is then allowed to charge or discharge the capacitor. In this way you minimize antenna effects caused by long distances from the analog source that would normally interfere during a sample period.
}}
CON
    _CLKMODE = XTAL1 + PLL16X
_XINFREQ = 5_000_000
        Drive = 1
                                                               'sigma-delta feedback
        Feedback = 0
                                                               'sigma-delta input
0BJ
PST
                             : "Parallax Serial Terminal"
VAR
Long
               Sample
PUB start
       PST.Start(19200{<- Baud})
       cognew (@PASM, @Sample)
        repeat
           PST.dec(Sample)
           PST.Char(13{<- Return character})
DAT
PASM
                           andn
                                                                 _Drive
                                                                                              'Set Drive pin to an input
                                                                                              'Clear ADC_Sample
'Set number of itterations
'Read ADC feedback pin ; set Z flag
'Preset drive pin to opposite state of feedback pin
ADC_Start
                           mov
                                               ADC_sample,#0
                           mov
                                               Counter, samples
ADC_I oop
                           test
                                               _FB,
                                                              ina wz
                                                              _Dri ve
                           muxz
                                               outa,
                           or
andn
                                                             _Drive
_Drive
                                                                                              'Set Drive pin to an output
'Set Drive pin to an input
                                               di ra,
                                               di ra,
                                                                                              'Increment ADC
'next itteration
'write ADC_sample back to Spin variable "sample"
'read next ADC sample
                                              ADC_sample, #1
Counter, #ADC_loop
ADC_sample, par
#ADC_Start
                           add
               if_z
                           dj nz
                           wrlong
                           imp
ADC sample
                           Long
                                               0
Counter
                           Long
samples
                           long
                                               1000
                                                                                               'Range ; Adjust this to suit the output range that you need
                                                                                                                i.e. For measuring voltage, a value of 3300 might be convienient to display the result in mV
_FB
_Drive
                           long
                                               |<Feedback
                           long
                                                <Drive
DAT
```

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\[date]

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