



**Catalina**  
**Catalyst Operating System**  
**Reference Manual**

**Release 2.5**

## Table of Contents

<b>WHAT IS CATALYST?</b> .....	<b>3</b>
STATUS .....	3
FEATURES .....	3
LICENSE .....	3
<b>INSTALLING CATALYST</b> .....	<b>4</b>
OVERVIEW .....	4
INSTALLING THE CATALYST BINARY RELEASE .....	4
<i>Load the Catalyst binary into EEPROM</i> .....	4
<i>Load the Catalyst programs onto an SD Card</i> .....	4
INSTALLING THE CATALYST SOURCE RELEASE .....	5
<i>Catalyst Directory Structure</i> .....	5
<i>Building Catalyst from source</i> .....	5
<i>Compiling Programs for Catalyst</i> .....	6
Compiling C programs to run under Catalyst .....	6
Compiling SPIN programs to run under Catalyst .....	6
<b>USING CATALYST</b> .....	<b>7</b>
USING THE CATALYST LOADER .....	7
CATALYST COMMANDS .....	7
<i>Catalyst Internal Commands</i> .....	7
DIR .....	7
CLS .....	7
CAT .....	7
HELP .....	8
<i>Catalyst External Commands</i> .....	8
LS .....	8
MV .....	8
RM .....	9
CP .....	9
MKDIR .....	9
RMDIR .....	10
<i>Catalyst Optional Commands</i> .....	10
BOOT_n .....	10
RESET_n .....	10
CATALYST APPLICATIONS .....	11
DUMBO BASIC .....	11
LUA .....	11
JZIP .....	11
PASCAL .....	12
SUPER STAR TREK .....	12
VI .....	12
<b>PLATFORM-SPECIFIC NOTES</b> .....	<b>14</b>
DRACBLADE .....	14
HYBRID .....	14
MORPHEUS .....	15
RAMBLADE .....	17
TRIPLADEPROP .....	17
<b>CATALYST DEVELOPMENT</b> .....	<b>19</b>
REPORTING BUGS .....	19
IF YOU WANT TO HELP DEVELOP CATALYST .....	19
OKAY, BUT WHY IS IT CALLED "CATALYST"? .....	19
ACKNOWLEDGMENTS .....	19
<b>THE CURRENT CATALYST RELEASE</b> .....	<b>20</b>
WHAT'S NEW IN THIS RELEASE? .....	20
WHAT'S DUE IN THE NEXT RELEASE? .....	20

## What is Catalyst?

Catalina is an SD card-based program loader, plus a set of utility programs for the Parallax Propeller.

When used as intended, Catalyst looks very much like a fully functional Propeller operating system. However, strictly speaking, Catalyst is *just* a program loader - it is not really a true operating system because it does no resource management - however, it can be used to load programs that *do* perform various common resource management tasks – it even comes with a few - e.g. various utilities for doing SD card file management.

While it can be used with any Propeller programs, Catalyst is specifically intended to facilitate loading and using programs compiled with the Catalina C compiler.

It is not currently possible to compile Catalina C programs *on* the Propeller, but Catalyst comes with various other applications that can be used for self-hosted Propeller development, including the vi text editor, and such tools as a BASIC interpreter, a Pascal compiler and interpreter, and the Lua scripting language. It could also be use to edit, compile and then run SPIN programs using with the Sphinx SPIN compiler (not included – see <http://www.sphinxcompiler.com/>).

## Status

Catalyst Release 2.5 is actually the first full release of Catalyst. It is numbered 2.5 to coincide with *Catalina* 2.5, which is the release of Catalina that incorporates support for some of the Catalyst specific features (such as the ability to accept command line arguments).

## Features

- Compatible with any Propeller platform that supports Catalina and has an SD card;
- Provides familiar SD card file management (e.g. ls cp, mv, rm, mkdir, rmdir)
- Can be used with SPIN or Catalina LMM programs on any platform;
- Support for Catalina XMM programs on those platforms that have external XMM RAM (e.g. Hybrid, TriBladeProp, RamBlade, Morpheus);
- Support for multi-CPU platforms (e.g. TriBladeProp, Morpheus);
- Supports self-hosted Propeller development (in Pascal, Basic and Lua).
- Supports passing command line parameters to both C and SPIN programs.

## License

All components of Catalyst are free and open source. Many of the components are licensed under the MIT license. Others are free but are licensed under the GNU General Public License, or other terms and conditions. All licenses are open-source, and free for non-commercial use – however, they are subject to various copyright and other conditions and you should consider the license terms of each component before using any of them in a commercial application.

## Installing Catalyst

### Overview

There are two mandatory parts to Catalyst, and one optional part that may need to be installed:

From the binary release:

- The main Catalyst binary. This should be programmed into the EEPROM of the propeller. There will be a different version for each platform, and is distributed as part of the binary release for each specific propeller platform.
- The Catalyst external command and application program binaries. These programs should be loaded onto an SD card. They are distributed as part of a binary release for a specific propeller platform.

From the source release (optional):

- The Catalyst source code. This is distributed as part of the normal Catalina source release. It may also be distributed separately. In either case, it should be installed in the normal Catalina program directory.

### *Installing the Catalyst Binary Release*

#### Load the Catalyst binary into EEPROM

The main Catalyst binary (**catalyst.binary**) is called **catalyst.bin** in the binary release. This should be programmed into the EEPROM of the propeller. This can be done using the Catalina payload program if the Propeller is connected and turned on, using a command like:

```
payload -e catalyst.bin
```

#### Load the Catalyst programs onto an SD Card

The remaining contents of the binary release must be copied an SD card (or micro SD card) that is inserted into the Propeller.

This SD card must be formatted with a FAT file system. However, neither Catalyst nor Catalina support long file names, so all **.binary** file names must be renamed to be no longer than 8 characters, and have an extension of **.bin**.

Catalyst allows binary programs to be stored in a **/bin** directory on the SD card. If the program to be loaded exists in the root directory of the SD card then that version is loaded, otherwise Catalyst attempts to load the program from the **bin** directory (if it exists).

When copying the **.bin** binary files to an SD card, binary files can be either in the root directory, or within a **bin** directory. The rest of the files in the binary release should be copied to the root directory of the SD card.

## Installing the Catalyst Source Release

There is no installer for the Catalyst source release. If Catalyst is distributed separately from Catalina, simply use **unzip** (Windows version) or **gzip/tar**<sup>1</sup> (Linux version) to extract the source distribution into the folder in which Catalina is to be installed.

Under Windows, Catalyst should be installed in **C:\Program Files\Catalina\catalyst** and under Linux it should be installed in **\usr\local\lib\catalina\catalyst**.

Installing to a directory other than the default location is possible, but it means that some additional options will need to be specified (or some scripts modified) when compiling Catalyst.

Note that Catalyst 2.5 requires Catalina 2.5 – it should not be used with earlier versions of Catalina.

## Catalyst Directory Structure

When Catalyst is installed, the directory structure should be as follows:

```

Catalina
|
+--- catalyst
|
|   .
|   .
|   .
|   +--- bin
|   +--- core
|   +--- dumbo_basic
|   +--- jzip
|       |
|       +--- doc
|   +--- lua-5.1.4
|       |
|       +--- doc
|       +--- etc
|       +--- src
|       +--- test
|   +--- pascal
|       |
|       +--- p5_c
|       +--- p5_pascal
|       +--- ptoc
|   +--- demo
|   +--- sst
|   +--- xvi-2.47
|       |
|       +--- doc
|       +--- src

```

## Building Catalyst from source

The **catalyst** directory contains a **build\_all** script that can be used to build all platforms except **MORPHEUS** – for that platform there is a special **build\_morpheus** script. For example, some commands to build Catalyst would be:

```

build_all HYBRID
build_all TRIBLADEPROP CPU_2 PC VT100

```

<sup>1</sup> Note that when using **tar**, the **-p** tar option should be specified to preserve file permissions.

### `build_morpheus`

To build Catalyst you will require Catalina, MinGW and MSYS installed. Refer to the Catalina reference manual for more details on MinGW and MSYS.

See the **README.TXT** file in the **catalyst** directory for more details, and also the **README** files in each of the application directories.

## Compiling Programs for Catalyst

The main features Catalyst adds to existing programs is the ability to invoke them to run from the SD card, and accept command line parameters. This functionality is available both to Catalina C programs as well as SPIN programs.

### *Compiling C programs to run under Catalyst*

Nothing special is required to make C programs run under Catalyst. Any parameters specified on the Catalyst command line will be available to the C program in the normal **argc** and **argv** parameters.

An example program (**demo.c**) is contained in the **demo** directory. To compile it, use a command like:

```
catalina demo.c -lc -D HYBRID
```

### *Compiling SPIN programs to run under Catalyst*

To enable SPIN programs to interpret command line parameters, a special SPIN module is provided **Catalyst\_Arguments.spin**.

An example program (**demo.spin**) is contained in the **demo** directory. To compile it, use any SPIN compiler to produce a binary output. For example, to use homespun:

```
homespun demo.spin -b
```

Note that the example program must be manually modified to suit the platform on which you intend to run it – by default it is configured to run on a **HYBRID**. The clock speed, pins and perhaps the TV and video drivers will need to be modified to suit other platforms.

The **Catalyst\_Arguments** module provides three methods:

**init(buffer)** *buffer* must point to a buffer of 1200 bytes (300 longs). This method must be called before any of the other argument methods.

**argc** this function returns the number of arguments (which may be zero).

**argv(i)** this function returns a pointer to a zero terminated string that contains the *i*th command line argument.

## Using Catalyst

### *Using the Catalyst Loader*

The main Catalyst binary is executed whenever the propeller is reset. It should display a simple banner line similar to the following:

```
Catalyst v1.1  
>
```

Where this prompt appears will differ depending on the Propeller platform. For example, on the **RAMBLADE** the Catalyst HMI uses a serial terminal emulator (e.g. on a PC), whereas on the **HYBRID** Catalyst will a local TV display and PS/2 keyboard. On other platforms, Catalyst may use either a serial terminal, or a local TV or VGA display and keyboard depending on the configuration parameters used when Catalyst is compiled. See the notes on each supported platform given later in this document.

When Catalyst is configured to use the PC serial terminal emulator HMI option, some of the commands expect a VT100 compatible terminal emulator. The recommend terminal emulator is **putty** - it is free, and versions for Windows are available from:

```
http://www.chiark.greenend.org.uk/~sgtatham/putty/download.html
```

At this point, Catalyst commands can be entered. Catalyst contains a few simple *internal* commands (e.g. **dir**, **cat**, **help**) described below, but most of the Catalyst commands are *external* commands, loaded from the SD card.

Note that whenever the SD Card is removed and re-inserted, Catalyst must be reset. Otherwise the SD file system access will not work correctly.

### **Catalyst Commands**

#### **Catalyst Internal Commands**

The internal commands are built into the Catalyst loader. They will work on any Propeller platform supported by Catalina.

Note that when using a local display and keyboard, all the internal commands will pause after each screen full of information has been displayed, and require you to press a key to continue. This is not the case when using the PC terminal HMI.

#### **DIR**

Display the files in the SD card root directory. This command does not accept any parameters, so only files in the root directory are displayed. For a more comprehensive display, see the LS command.

#### **CLS**

Clear the screen.

For CLS to work correctly when using a PC HMI, a VT100 compatible terminal emulator (such as putty) must be used.

#### **CAT**

Display a text file. On platforms that use a local display, the file is displayed one page at a time. The ESC key can be used to exit at each pause.

## HELP

Display some simple help about the various internal commands.

## Catalyst External Commands

The external commands may be normal SPIN programs or LMM C programs. They will work on any Propeller platform supported by Catalina. They do not require XMM RAM, but they depend on being loaded by Catalyst so that command line arguments can be entered.

## LS

list the details of a file or the contents of a directory.

syntax:

```
ls [options] [directory]
```

options:

```
-h or -?    print help
-l          long format listing
-r          recursively list subdirectories
```

e.g. to list the current (top level) directory:

```
ls
```

or

```
ls .
```

To list directory a/b/c:

```
ls a/b/c
```

## MV

Move one file to another, or one or more files to a directory. If there are only two arguments, and the target does not exist, you must tell mv whether the target is supposed to be a file or a directory.

NOTE: mv is essentially a cp followed by an rm - with the rm only performed if the copy succeeds. This means that there must be enough free space to hold two complete copies of the file.

syntax:

```
mv [options] src_file [src_file ...] target_file_or_directory
```

options:

```
-h or -?    print help
-f          force overwrite (if target is read-only)
-I          interactive (prompt for each move)
-t          target is a directory
-T          target is a file
```

e.g:

```
mv a.txt b.txt c.txt my_dir
```

```
mv a.txt b.txt
```

**RM**

Remove one or more files, optionally also removing directories (provided they are empty).

syntax:

```
rm [options] file_or_directory ...
```

options:

```
-h or -?    print help
-f          remove empty directories
```

e.g:

```
rm a/b.txt
rm a.txt b.txt
```

**CP**

Copy one file to another, or one or more files to a directory. If there are only two arguments, and the target does not exist, you must tell cp whether the target is supposed to be a file or a directory.

syntax:

```
cp [options] src_file [src_file ...] target_file_or_directory
```

options:

```
-h or -?    print help
-f          force overwrite (if target is read-only)
-I          interactive (prompt for each copy)
-t          target is a directory
-T          target is a file
```

e.g:

```
cp a.txt b.txt c.txt my_dir
cp a.txt b.txt
```

**MKDIR**

Make one or more directories, optionally making each parent directory in turn if they do not exist.

syntax:

```
mkdir [options] directory ...
```

options:

```
-h or -?    print help
-p          create parent directories if required
```

e.g:

```
mkdir a/b/c    <- will make directory c only if a/b exists
mkdir -p a/b/c <- will make directories a, then a/b,
                then a/b/c if they do not already exist
```

**RMDIR**

Remove one or more directories, optionally removing each parent directory recursively (if they are empty).

syntax:

```
rmdir [options] directory ...
```

options:

```
-h or -?      print help
-p           remove parent directories if empty
```

e.g. to remove directory c (but leave a and b intact):

```
rmdir a/b/c
```

To remove directory a/b/c, then a/b, then a (provided they are empty):

```
rmdir -p a/b/c
```

**Catalyst Optional Commands**

On platforms that contain multiple CPUs (such as the **TRIBLADEPROP**, or **MORPHEUS**) it may be convenient to have the normal Catalina multi-CPU utilities loaded onto the Catalyst SD card.

Note that the relevant Catalina utilities are called **CPU\_n\_Boot.spin** and **CPU\_n\_Reset.spin**, and when compiled they may be called something like **BOOTn.m** (e.g. **BOOT2.1**) - but for Catalyst they should be renamed to simply **BOOT\_n.bin** or **RESET\_n.bin** when the compiled binaries are copied to the SD card (this is not absolutely required, but convention Catalyst uses **.bin** as an executable file name extension).

**BOOT\_n**

Reboot the specified Propeller, loading the Catalina Generic SIO Binary Loader so that another program can be loaded.

syntax:

```
boot_1          (TRIBLADEPROP only)
boot_2          (MORPHEUS only)
boot_3          (TRIBLADEPROP only)
```

**RESET\_n**

Just reset the specified Propeller. Whatever program is loaded into EEPROM will be run.

syntax:

```
reset_1         (TRIBLADEPROP only)
reset_2         (MORPHEUS only)
reset_3         (TRIBLADEPROP only)
```

## **Catalyst Applications**

Catalyst provides a rich set of application programs. All the example applications provided require at least 512k of XMM RAM to be installed.

This section does not describe each application in detail – it only describes how to run the application programs from the Catalyst command line. See the individual application program documentation for more details on the application itself.

### **DUMBO BASIC**

Load the Dumbo BASIC interpreter. Note that Dumbo BASIC is just an interpreter – the programs must be created externally (e.g. using the vi text editor).

syntax:

```
dbasic [ basic_program.bas ]
```

e.g:

```
dbasic eliza.bas
```

If no parameter is specified, dbasic will prompt for the name of the basic file to execute.

### **LUA**

Load the Lua interpreter (**lua**), or run the Lua compiler (**luac**).

syntax:

```
lua [script.lua]
```

```
luac -o output_filename script.lua
```

e.g:

```
lua fact.lua
```

```
luac -o f.lua fact.lua
```

If no file is specified to the **lua** command, commands can be entered directly on the terminal.

The Lua compiler (**luac**) compiles a Lua program to byte code, which speeds up loading – but the resulting file must still be executed with **lua**.

NOTE: when using **luac**, do not omit the **-o** parameter, or **lua** will output the binary result to the terminal.

### **JZIP**

Load the JZIP Infocom game interpreter. The number of rows and columns to use for the screen size can be specified on the command line, but the game will detect the actual screen size when local devices are used, and assume 80x24 when using the PC HMI option.

syntax:

```
jzip [-ccols] [-lrows] [ game.dat ]
```

e.g:

```
jzip zork1.dat
```

If no parameter is specified, jzip will prompt for the name of the game file to execute.

## **PASCAL**

Load the Pascal interpreter (**pint**), or run the Pascal compiler (**pcom**).

syntax:

```
pint [compiled_program]
pcom [ program_to_compile [compiled_program] ]
```

e.g:

```
pint startrek.p5
pcom startrek.pas startrek.p5
```

The output files from the compiler must be executed with the interpreter.

If no file is specified to the **pcom** or **pint** commands, the programs will prompt for a file name.

By convention, the compiled version of the Pascal program **prog.pas** is normally called **prog.p5**

In addition to a few sample programs, two precompiled programs are provided – **startrek.p5** and **basics.p5**. The first is yet another version of the classic Start Trek game and the second is a basic interpreter. These programs are provided compiled because they can each take several hours to compile on the Propeller – even loading the precompiled programs can take a minute or two.

## **SUPER STAR TREK**

Play a game of Super Star Trek.

syntax:

```
sst
```

There are no parameters to this command. See the document sst.doc for help.

## **VI**

Load the XVI text editor (the binary renamed to vi for convenience). The program accepts various options – see the xvi documentation for more details.

syntax:

```
vi [options] [ filename ... ]
```

e.g:

```
vi sample1.txt
```

A common option to specify is **-s format=msdos** or **-s format=unix** to specify whether msdos or unix line termination is to be used (the default is unis, so if you open an msdos file you may see extraneous **^M** characters at the end of each line).

If more than one filename is specified, vi will open the first two in separate windows. After that, use **:n** (i.e. *colon n*) to move to the next file.

## Platform-specific Notes

### *DracBlade*

On the DracBlade, all the Catalyst binaries are built to use a High resolution VGA HMI plugin, which uses the display and keyboard connected to the Propeller.

Note: After each external command or demo program is run, the screen is cleared. Catalyst will usually ask you to enter a key to continue so that you can read the output of the command.

Here are some example commands you could try:

```

cat SAMPLE.PAS          <---- list a text file
pcom SAMPLE.PAS SAMPLE.P5 <---- compile a pascal program
pint SAMPLE.P%         <---- run the compiled program
vi CATALYST.TXT        <---- edit a text file
dbasic STARTREK.BAS    <---- run a basic program
mkdir my_dir           <---- make a directory
vi my_dir/my_file.txt  <---- edit a file in a directory
ls my_dir              <---- list the contents of a directory
rm my_dir/my_file.txt  <---- remove a file from a directory
jzip ZORK3.DAT         <---- play a game of Zork
sst                   <---- play a game of Super Star Trek
dbasic ELIZA.BAS      <---- get some psychiatric help

```

On the DracBlade, it is possible to recompile Catalyst (or some parts of Catalyst) to use a PC HMI option (or a low resolution VGA option). This may be required to run some large applications (such as the Pascal compiler) since the High Resolution VGA driver consumes a large amount of Hub RAM space, which limits the stack space available to other programs.

### *Hybrid*

All the binaries in this release (as well as Catalyst itself) are built to use a High resolution NTSC TV and keyboard connected to the Propeller emulator.

Note: After each external command or demo program is run, the screen is cleared. Catalyst will usually ask you to enter a key to continue so that you can read the output of the command.

Here are some example commands you could try:

```

cat SAMPLE.PAS          <---- list a text file
pcom SAMPLE.PAS SAMPLE.P5 <---- compile a pascal program
pint SAMPLE.P%         <---- run the compiled program
vi CATALYST.TXT        <---- edit a text file
dbasic STARTREK.BAS    <---- run a basic program
mkdir my_dir           <---- make a directory
vi my_dir/my_file.txt  <---- edit a file in a directory

```

```

ls my_dir          <---- list the contents of a directory
rm my_dir/my_file.txt  <---- remove a file from a directory
jzip ZORK3.DAT     <---- play a game of Zork
sst               <---- play a game of Super Star Trek
dbasic ELIZA.BAS  <---- get some psychiatric help

```

On the Hybrid, it is **NOT** possible to recompile Catalyst to use a PC HMI option if the XMM RAM is being used – the HX512 does not allow the serial port to be used at the same time.

## **Morpheus**

On Morpheus, Catalyst is configured to use the PC HMI option, and some programs expect a VT100 compatible PC Terminal emulator (such as **putty**).

On Morpheus, running the external commands often results in rubbish being displayed on the screen at the end of each command - this is because each external command resets the Propeller at the end. This means you may need to scroll the putty screen up to see the output of the command. While this is a little annoying, it does not really affect the operation of Catalyst.

What *does* makes thing complex on Morpheus is that Catalyst runs on CPU #1, but the demo programs must be run on CPU #2 since they all require access to XMM RAM. They must use Catalina proxy drivers since they need access to both the XMM RAM and the SD Card.

The binary distribution of Catalyst also includes the normal Catalina multi-cpu utilities for Morpheus (renamed to be a bit more user-friendly):

```

BOOT_2.BIN - start a boot loader program running on CPU #2
RESET_2.BIN - reset CPU #2
LOAD_2.BIN - SIO Loader (can be programmed into EEPROM on CPU #2)

```

The following explains how to run each Catalyst demo program:

**vi** - the client executable runs on CPU\_2, using the SD card on CPU\_1. This can make editing a bit slow on large files! To run it, you need to load both the client and the server. If you have not already done so, you also first need to load the boot loader into CPU #2:

```

boot_2          <- load the boot loader into CPU #2
@              <- to select CPU #2 for next load
vi             <- load the client into CPU #2
proxy         <- load the server into CPU #1

```

There are a few things to note about loading/running this program:

1. If you program the Generic SIO program loader (**load\_2.bin**) into the eeprom of CPU #2, you do not need to enter any of the **boot\_2** commands – loading the SIO loader into CPU #2 is really all the **boot\_2** program does.
2. You will see progress messages displayed on the PC as the client program is loaded.
3. You may see rubbish on the screen when the client program starts up (and before you get a chance to start the proxy server) – this occurs when the

program loader restarts the Propeller to run the loaded program. In some cases, these rubbish characters can cause the terminal emulator program (e.g. putty) to lock up – just restart the terminal emulator and everything should be ok.

4. You cannot currently use command line parameters for programs loaded into another CPU - e.g. you cannot pass parameters to the **vi** client. Instead, to edit a particular file, once **vi** starts you can enter the command:

```
:e filename
```

5. Just because you quit a demo client program (i.e. **vi**) does not mean you will return to the Catalyst prompt. This is because the proxy program is still running. Since there is currently no way to tell the proxy program to terminate, to return to the Catalyst prompt you must manually reset the Propeller.
6. If you accidentally try to run the **vi** client on CPU #1, you will see a series of **ÿÿÿÿ** characters - this is the client program polling for the proxy server. You will have to manually reset the prop.

**sst** -you must run the client on CPU #2, and the proxy server on CPU #1:

```
boot_2          <- load the boot loader into CPU #2
@              <- to select CPU #2 for next load
sst            <- load the client into CPU #2
proxy         <- load the server into CPU #1
```

The same provisos apply as above - i.e. you cannot enter command line arguments to the client, and you must reboot the Propeller to return to the Catalyst prompt.

**jzip** - you must run the client on CPU #2, and the proxy server on CPU #1:

```
boot_2          <- load the boot loader into CPU #2
@              <- to select CPU #2 for next load
jzip           <- load the client into CPU #2
proxy         <- load the proxy server into CPU #1
```

The same provisos apply as above - i.e. you cannot enter command line arguments to the client, and you must reboot the Propeller to return to the Catalyst prompt. The program will prompt you for a game file to run.

**dbasic** - you must run the client on CPU #2, and the proxy server on CPU #1:

```
boot_2          <- load the boot loader into CPU #2
@              <- to select CPU #2 for next load
dbasic         <- load the client into CPU #2
proxy         <- load the proxy server into CPU #1
```

The same provisos apply as above - i.e. you cannot enter command line arguments to the client, and you must reboot the Propeller to return to the Catalyst prompt. The program will prompt you for a basic file to run.

**pcom/pint** - you must run the clients on CPU#2, and the proxy server on CPU #1:

```
boot_2          <- load the boot loader into CPU #2
@              <- to select CPU #2 for next load
pcom           <- load the compiler client into CPU #2
```

```

    proxy                <- load the proxy server into CPU #1
or
    boot_2               <- load the boot loader into CPU #2
    @                   <- to select CPU #2 for next load
    pint                <- load the interpreter client into CPU #2
    proxy               <- load the proxy server into CPU #1

```

The same provisos apply as above - i.e. you cannot enter command line arguments to the client, and you must reboot the Propeller to return to the Catalyst prompt. The program will prompt you for a Pascal file to compile or interpret.

**lua** -you must run the client on CPU #2, and the proxy server on CPU #1:

```

    boot_2               <- load the boot loader into CPU #2
    @                   <- to select CPU #2 for next load
    lua                 <- load the client into CPU #2
    proxy               <- load the server into CPU #1

```

The same provisos apply as above - i.e. you cannot enter command line arguments to the client, and you must reboot the Propeller to return to the Catalyst prompt. Use must use the Lua dofile command to get lua to execute a script (e.g. enter **dofile("hello.lua")** - see the Lua documentation, or the **README.Lua** file for more details.

### **RamBlade**

On the RamBlade, Catalyst is configured to use the PC HMI option, and some programs expect a VT100 compatible PC Terminal emulator (such as **putty**).

Here are some example commands you could try:

```

    cat SAMPLE.PAS      <---- list a text file
    pcom SAMPLE.PAS SAMPLE.P5 <---- compile a pascal program
    pint SAMPLE.P%     <---- run the compiled program
    vi CATALYST.TXT    <---- edit a text file
    dbasic STARTREK.BAS <---- run a basic program
    mkdir my_dir       <---- make a directory
    vi my_dir/my_file.txt <---- edit a file in a directory
    ls my_dir          <---- list the contents of a directory
    rm my_dir/my_file.txt <---- remove a file from a directory
    jzip ZORK3.DAT     <---- play a game of Zork
    sst                <---- play a game of Super Star Trek
    dbasic ELIZA.BAS   <---- get some psychiatric help

```

### **TriBladeProp**

On the TriBladeProp, Catalyst is configured to use the PC HMI option, and some programs expect a VT100 compatible PC Terminal emulator (such as **putty**).

Here are some example commands you could try:

```

    cat SAMPLE.PAS      <---- list a text file

```

```
pcom SAMPLE.PAS SAMPLE.P5 <---- compile a pascal program
pint SAMPLE.P%           <---- run the compiled program
vi CATALYST.TXT          <---- edit a text file
dbasic STARTREK.BAS     <---- run a basic program
mkdir my_dir             <---- make a directory
vi my_dir/my_file.txt    <---- edit a file in a directory
ls my_dir                <---- list the contents of a directory
rm my_dir/my_file.txt    <---- remove a file from a directory
jzip ZORK3.DAT           <---- play a game of Zork
sst                       <---- play a game of Super Star Trek
dbasic ELIZA.BAS         <---- get some psychiatric help
```

It would be possible to recompile Catalyst to use the local display and keyboard on CPU #1, via a proxy driver from CPU #2 (which has access to the SD card). The various **build\_morpheus** scripts show this can be accomplished using proxy devices.

## Catalyst Development

### ***Reporting Bugs***

Please report all Catalyst bugs to [ross@thevastydeep.com](mailto:ross@thevastydeep.com).

Where possible, please include a *brief* example that demonstrates the problem.

### ***If you want to help develop Catalyst***

Anyone who has ideas or wants to assist in the development of Catalyst should contact Ross Higson at [ross@thevastydeep.com](mailto:ross@thevastydeep.com)

### ***Okay, but why is it called “Catalyst”?***

In chemistry a catalyst is a substance that facilitates a chemical reaction, but is not itself consumed. Catalyst is intended to facilitate the use of Catalina on the Propeller, but it does not itself consume any Propeller resources.

### ***Acknowledgments***

Kye, for his FATEngine module.

## The Current Catalyst Release

### ***What's new in this release?***

- Everything is new - this is the first release!

### ***What's due in the next release?***

- Add wildcard support to ls, cp, mv and rm
- Add 'flush' so that we don't have to wait for a fixed duration after each command when using the PC HMI option.
- Add a way to exit from the proxy program, so we don't always have to reset the propeller after each proxied command.