

PropBASIC 00.00.25 Nov 9, 2009

Operators

Unary Operators:

ABS	Returns the absolute value
SGN	Returns the sign of value 1, 0, -1

Binary Operators:

+	Addition
-	Subtraction
*	Multiplication
/	Division
//	Remainder
*/	Multiply, shift 16-bits
**	Multiply, shift 32-bits
& AND	Bitwise AND
OR	Bitwise OR
^ XOR	Bitwise XOR
&~ ANDN	Bitwise AND NOT
MIN	Minimum of two values
MAX	Maximum of two values
>> SHR	Shift right
<< SHL	Shift left

DEVICE Sets device type and parameters.

DEVICE *deviceID*, {*settings*{,*settings*}}

DEVICE P8X32A, XTAL1, PLL16X

deviceID: only P8X32A is supported

settings: RCSLOW, RCFast, XINPUT, XTAL1..3, PLLX2, PLLX4, PLLX8, PLLX16

FREQ Sets device frequency after pll multiplier.

FREQ *freq*

FREQ 80_000_000

* Do not use FREQ and XIN together, use one or the other

XIN Crystal frequency before pll multiplier

XIN *freq*

XIN 5_000_000

* Do not use FREQ and XIN together, use one or the other

DATA, WDATA, LDATA Creates data values in HUB ram. DATA = BYTE, WDATA=WORD, LDATA=LONG

[*label*] DATA *value1*[,*value2*[,*value3*[,*etc*]]]

BitMask DATA 1,2,4,8,16

* Data labels MUST be on the same line as the DATA command.

HUB Creates HUB variables. Access via GETADDR, RDBYTE, RDWORD, RDLONG, WRBYTE, WRWORD, WRLONG

name HUB *type* [= *value*]

name HUB *type*(*elements*) [= *value*]

myVar HUB LONG = 100_000

myVars HUB LONG(8) = 0

type: BYTE, WORD, LONG

* Use RDBYTE, RDWORD, RDLONG to read value from HUB variables.

* Use WRBYTE, WRWORD, RDLONG to write value to HUB variables.

CON Creates a named constant

name CON *value*

MyCon CON 1000

VAR Creates a variable. Only LONG types are supported. Arrays are supported.

```
name VAR LONG
name VAR LONG(elements)
myVar VAR LONG
myVar VAR LONG(8)
```

PIN Creates a pin variable. #name = pin number, @name = pin mask

```
name PIN pinnumber [modifier]
LED PIN 0 LOW
* modifiers: INPUT, OUTPUT, HIGH, LOW
```

FUNC...ENDFUNC Creates a named function. Returns 1 LONG value.

```
name FUNC [minParams[,maxParams]]
FUNC name
...
ENDFUNC
```

```
Calc FUNC 1
```

```
myVar = Calc 1
```

```
FUNC Calc
__param1 = __param1 + 1

RETURN __param1
ENDFUNC
```

SUB...ENDSUB Creates a named subroutine

```
name SUB [minParams[,maxParams]]
SUB name
...
ENDSUB
```

```
SetDAC SUB 1
```

```
SetDAC 1
```

```
SUB SetDAC
' code to set DAC
ENDSUB
```

TASK...ENDTASK Creates code that runs in a separate cog.

```
name TASK
```

```
TASK name
```

```
...
ENDTASK
```

```
* Task code runs in a separate cog.
* VAR variables are not shared between cogs.
* SUBs and FUNCs are not shared between cogs.
* HUB variables and DATA is shared between cogs.
```

NOP No operation. Does nothing. Uses 1 instruction.

```
NOP
```

**** Creates a single line of propeller assembly code.

```
\ ROR myVar, #1
```

ASM...ENDASM Creates a block of propeller assembly code.
ASM
...
ENDASM

' Creates a comment.

INPUT Makes a pin an input.
INPUT *pinname* | *const*
INPUT switch
INPUT 0

OUTPUT Makes a pin an output.
OUTPUT *pinname* | *const*
OUTPUT LED
OUTPUT 1

REVERSE Reverse pin direction (input / output)
REVERSE *pinname* | *const*
REVERSE sensor
REVERSE 2

HIGH Makes a pin an output and high.
HIGH *pinname* | *const*
HIGH LED
HIGH 3

LOW Makes a pin an output and low.
LOW *pinname* | *const*
LOW LED
LOW 4

TOGGLE Toggles pin state (high / low)
TOGGLE *pinname* | *const*
TOGGLE LED
TOGGLE 5

BRANCH Variable determines what label to jump to.
BRANCH *var*, *label0*, *label1*, *label2*[, *label3*[,etc]]

STR Converts a variable to ASCII characters.
STR *array*, *var*, *digits*

Ascii VAR LONG (6)
Value VAR LONG
STR *ascii*, *value*, 6

PROGRAM Sets program start label.
PROGRAM *label*
PROGRAM Start

INCLUDE Includes propeller assembly code from a separate file.

LOAD Load PropBASIC code from a separate file.

PAUSE Pauses for milliseconds.
PAUSE *value*
PAUSE 1000

PAUSEUS Pauses for microseconds. Can use fractional value.
PAUSEUS *value*
PAUSEUS 1000
PAUSEUS 4.7

END Ends program execution.
END

INC Adds 1 to a variable.
INC *varname*

cntr VAR LONG
INC cntr

DEC Subtract 1 from a variable.
DEC *varname*

cntr VAR LONG
DEC cntr

GOTO Jump to a label.
GOTO *label*
GOTO Start

GOSUB Jump to a subroutine.
GOSUB *label*

GOSUB Calc

Calc:
 ' Code
 RETURN *value*
* It is recommended to use named subroutines instead of GOSUB.

RETURN Return from a subroutine.
RETURN [*value*]
RETURN 1

LET Optional

IF...ELSE|ELSEIF...ENDIF
 IF *var cond value* THEN *label*
 IF *var cond value* THEN
 ' code
 ENDIF
 IF *var cond value* THEN
 ' code
 ELSE
 ' code
 ENDIF
 IF *var cond value* THEN
 ' code

```
ELSEIF var cond value THEN
  ' code
ELSE
  ' code
ENDIF
```

DO...LOOP

```
DO WHILE var cond value
LOOP

DO
LOOP UNTIL var cond value

DO
LOOP
```

FOR...TO...STEP...NEXT

```
FOR var = startvalue TO endvalue
  ' Code
NEXT
FOR var = startvalue TO endvalue STEP deltavalue
  ' Code
NEXT
```

EXIT Ends the current DO...LOOP or FOR...NEXT loop.

```
EXIT
IF var cond value THEN EXIT
```

RANDOM Creates a random number from a seed variable.

```
RANDOM seedvar[, copyvar]
```

SEROUT Serial output.

```
SEROUT pin, baud, char
```

SERIN Serial input.

```
SERIN pin, baud, var
```

SHIFTOUT SPI output.

```
SHIFTOUT datapin, clockpin, mode, value[\bits]
* mode: LSBFIRST, MSBFIRST
```

SHIFTIN SPI input.

```
SHIFTIN datapin, clockpin, mode, var[\bits]
* mode: LSBPRE, LSBPOST, MSBPRES, MSBPOST
```

RCTIME Measures time for pin to change state (in microseconds).

```
RCTIME pin, state, resultvar
```

PULSIN Measure incoming pulse width in microseconds

```
PULSIN pin, state, resultVar
```

PULSOUT Create a pulse of specified width.

```
PULSOUT pin, duration
```

DJNZ Decrease variable and jump to label if not zero.
 DJNZ *var, label*

I2CSTART Sends an I2C start condition.
 I2CSTART *SDAPin, SCLPin*

I2CSTOP Sends an I2C stop condition.
 I2CSTOP *SDAPin, SCLPin*

I2CREAD Reads a byte from the I2C buss.
 I2CREAD *SDAPin, SCLPin, var[, ackbitvalue]*

I2CWRITE Writes a byte to the I2C buss.
 I2CWRITE *SDAPin, SCLPin, value[, ackbitvar]*

OWRESET Sends a reset on the 1-wire buss.
 OWRESET *DQPin[, statusVar]*

OWRDBIT Reads a single bit from the 1-wire buss.
 OWRDBIT *DQPin, var*

OWRDBYTE Reads a byte from the 1-wire buss.
 OWRDBYTE *DQPin, var*

OWWRBIT Writes a single bit to the 1-wire buss.
 OWWRBIT *DQPin, value*

OWWRBYTE Writes a byte to the 1-wire buss.
 OWWRBYTE *DQPin, value*

ON...GOTO Jump to label based on value of a variable.
 ON *var* GOTO *label1, label2 [, label3, [, etc]]*
 ON *var = value1, value2, value3* GOTO *label1, label2, label3*

ON...GOSUB Same as ON...GOTO except does a subroutine jump.
 ON *var* GOSUB *label1, label2 [, label3, [, etc]]*
 ON *var = value1, value2, value3* GOSUB *label1, label2, label3*

GETADDR Gets address of a HUB variable or DATA.
 GETADDR *hubVar, var*

 sharedValues HUB LONG(8)

 valueAdr VAR LONG
 index VAR LONG
 temp VAR LONG

 GETADDR sharedValue, valueAdr
 valueAdr = valueAdr + index
 RDLONG valueAdr, temp

RDLONG Reads the value of a LONG hub variable or LDATA.
 RDLONG *longhubvar, var*

RDWORD Reads the value of a WORD hub variable or WDATA.
RDWORD *wordhubvar, var*

RDBYTE Reads the value of a BYTE hub variable or DATA.
RDBYTE *bytehubvar, var*

WRLONG Writes a new value into a LONG hub variable.
WRLONG *longhubvar, value*

WRWORD Writes a new value into a WORD hub variable.
WRWORD *wordhubvar, value*

WRBYTE Writes a new value into a BYTE hub variable.
WRBYTE *bytehubvar, value*

WAITCNT Waits for the system counter to reach the target value. Then adds the delta value to the variable.
WAITCNT *target, delta*

WAITVID Waits for the video serializer to be able to accept new data.
WAITVID *colors, pixels*

WAITPEQ Waits for a pin (or set of pins) state to equal a mask value.
WAITPEQ *state, mask*
* INA is anded with "mask" then compared to "state".

WAITPNE Waits for a pin (or set of pins) state to NOT equal a mask value.
WAITPNE *state, mask*
* INA is anded with "mask" then compared to "state".

COUNTERA / COUNTERB Setup hardware counter parameters.
COUNTERA *mode[, apin [, bpin[, frqx[, phsx]]]*

mode:
0 = Counter Disabled
8 = PLL Internal (Video) *
16 = PLL Single-Ended *
24 = PLL Differential *
32 = NCO/PWM Single Ended
40 = NCO/PWM Differential
48 = DUTY Single-Ended
56 = DUTY Differential
64 = POS detector
72 = POS detector with feedback
80 = POSEDGE detector
88 = POSEDGE detector with feedback
96 = NEG detector
104 = NEG detector with feedback
112 = NEGEDGE detector
120 = NEGEDGE detector with feedback
128 = LOGIC never
136 = LOGIC !A & !B
144 = LOGIC A & !B
152 = LOGIC !B
160 = LOGIC !A & B
168 = LOGIC !A
176 = LOGIC A <> B

```
184 = LOGIC !A | !B
192 = LOGIC A & B
200 = LOGIC A = B
208 = LOGIC A
216 = LOGIC A | !B
224 = LOGIC B
232 = LOGIC !A | B
240 = LOGIC A | B
248 = LOGIC always
```

```
* For PLL modes add:
0 = VCO / 128
1 = VCO / 64
2 = VCO / 32
3 = VCO / 16
4 = VCO / 8
5 = VCO / 4
6 = VCO / 2
7 = VCO / 1
```

General

Math operators can only be used when assigning values to a variable.

Math operators cannot be used in commands.

Only 1 math operator can be used per line.

Only LONG vars are supported. LONG arrays are supported.

Using a variable as an array index generates alot more code.

HUB vars can be BYTE, WORD or LONG. Arrays are supported.

HUB vars can ONLY be accessed with RDBYTE, WRBYTE, RDWORD, WRWORD, RDLONG, WRLONG commands.

Be aware that HUB vars must be address aligned by the size. So if you declare a BYTE then a LONG, there will be three wasted address location between them.

PINs, HUB vars and DATA are global to all COGs (tasks).

VARs, SUBs and FUNCs are local only to the TASK they are declared in.

All TASKS are started before the main code.

TASK code generates a seperate .spin file.

DATA must be declared before the program code. You cannot put the DATA after the program code.

Program template

```
DEVICE P8X32A, XTAL1, PLL16X
FREQ 80_000_000
```

```
' Define constants "name CON value"
' Define HUB vars "name HUB BYTE|WORD|LONG = value"
' Define DATA "label DATA value1, value2, etc"
' Define pins " name PIN value INPUT|OUTPUT|HIGH|LOW"
' Define TASKs "name TASK"
' Define vars "name VAR LONG = value"
' Define SUBs and FUNCs "name SUB minParams,maxParams"
```

```
PROGRAM START
```

```
START:
' Program code
END
```

```
' SUB and FUNC code
' SUB NAME
' code
' ENDSUB
```

```
' FUNC name
' code
' RETURN value
' ENDFUNC
```

```
' TASK code (remember TASK have private VARs, SUBs and FUNCs)
' TASK name
' code
' ENDTASK
```