

```
In[1]:= ser = DeviceOpen["Serial", {"/dev/ttyUSB0", "BaudRate" → 115200}]
close := DeviceClose[ser];
bclr := DeviceExecute[ser, "ReadFlush"];
rbuf := DeviceReadBuffer[ser];
```

SerialLink`SerialPortOpen: Could not open the port /dev/ttyUSB0.

```
Out[1]= $Failed
```

```
In[5]=
```

```
Spd$ := {"S1", "S2", "S3", "S4", "Sx"}
```

```
Cmd$ :=
```

```
 {"F", "B", "RR", "RL", "TR", "TL", "BTR", "BTL", "VR", "VL", "S", "H", "R", "RU", "RD"}
```

```
Dmd$ := {"M1", "M2", "GODT", "GSTEP", ">pos", "GF", "GB", "GRR", "GRL", "GTR", "GTL"}
```

```
Man$ := {"MAN1", "MAN2", "MAN3", "MAN4", "MAN5", "MAN6"}
```

```
In[9]= START := DeviceWrite[ser, {83, 84, 65, 82, 84, 13}]
```

```
FRWD := DeviceWrite[ser, {70, 82, 87, 68, 13}]
```

```
BKWD := DeviceWrite[ser, {66, 75, 87, 68, 13}]
```

```
RRWD := DeviceWrite[ser, {82, 82, 87, 68, 13}]
```

```
RLWD := DeviceWrite[ser, {82, 76, 87, 68, 13}]
```

```
GO := DeviceWrite[ser, {71, 79, 13}]
```

```
zenc := DeviceWrite[ser, {122, 101, 110, 99, 13}]
```

```
In[16]= F := {sCmd[1]; msg$ := " Moving Forward"}
```

```
B := {sCmd[2]; msg$ := " Moving Backward"}
```

```
RR := {sCmd[3]; msg$ = " Rotating Right"}
```

```
RL := {sCmd[4]; msg$ = " Rotating Left"}
```

```
TR := {sCmd[5]; msg$ = " Turning Right"}
```

```
TL := {sCmd[6]; msg$ = " Turning Left"}
```

```
BTR := {sCmd[7]; msg$ = " Backing to the Right"}
```

```
BTL := {sCmd[8]; msg$ = " Backing to the Left"}
```

```
VR := {sCmd[9]; msg$ = " Veering Right"}
```

```
VL := {sCmd[10]; msg$ = " Veering Left"}
```

```
S := {sCmd[11]; msg$ = " Stopped"}
```

```
H := {sCmd[12]; msg$ = " Halted"}
```

```
R := sCmd[13];
```

```
RU := {sCmd[14]; msg$ = "Ramping Up Speed"}
```

```
RD := {sCmd[15]; msg$ = "Ramping Down Speed"}
```

```
In[31]= S1 := {ldty = 150; rdy = 150; sSpd[1]}
```

```
S2 := {ldty = 250; rdy = 250; sSpd[2]}
```

```
S3 := {ldty = 500; rdy = 500; sSpd[3]}
```

```
S4 := {ldty = 750; rdy = 750; sSpd[4]}
```

```

In[35]:= msg1 := " Press START to Activate Robot Control"
msg2 := " STARTED - Robot Control Active"
msg3 := " REBOOTED - Press START to Continue"
msg4 := " Exercising Principal Motions "
msg5 := " Simple Avoidance Maneuver "
msg6 := " GamePad Mode "

msg$ := msg1

te := Dynamic [Clock[{0, 600, 1}]];

In[43]:= sSpd[no_] := DeviceWrite[ser, Append[ToCharacterCode[Spd$[[no]]], 13]];

sCmd[no_] := DeviceWrite[ser, Append[ToCharacterCode[Cmd$[[no]]], 13]];

sMan[no_] := DeviceWrite[ser, Append[ToCharacterCode[Man$[[no]]], 13]];

Sx[n1_, n2_] := DeviceWrite[ser, Join[{32}, ToCharacterCode[ToString[n1]], {32},
  ToCharacterCode[ToString[n2]], {32}, ToCharacterCode[Spd$[[5]]], {13}]];

GODT[n1_] :=
  DeviceWrite[ser,
    Join[ToCharacterCode[ToString[n1]], {32}, ToCharacterCode[Dmd$[[3]]], {13}]];

sDmd[no_, n1_] :=
  DeviceWrite[ser,
    Join[ToCharacterCode[ToString[n1]], {32}, ToCharacterCode[Dmd$[[no]]], {13}]];

STEP[n1_, n2_] :=
  DeviceWrite[ser, Join[{32}, ToCharacterCode[ToString[n1]], {32},
    ToCharacterCode[ToString[n2]], {32}, ToCharacterCode[Dmd$[[4]]], {13}]];

Rd$ := {".dist", ".lenc", ".renc"};

sRd[no_] := Block[{xe}, cbuf;
  DeviceWrite[ser, Append[ToCharacterCode[Rd$[[no]]], 13]];
  Pause[0.05]; xe := DeviceReadBuffer[ser];
  FromDigits[FromCharacterCode[Select[xe, # > 47 && # < 58 &]]];

In[52]:=
aa :=
  Panel[Row[{"ldty", {Slider[Dynamic[ldty], {100, 1000, 5}], Dynamic[ldty]}, " rdtty",
    {Slider[Dynamic[rdty], {100, 1000, 5}], Dynamic[rdty]}]},
    "Speed Settings (Sx)"];

bb := Framed[ButtonBar[{"Sx" => Sx[ldty, rdtty], "S1" => S1, "S2" => S2, "S3" => S3,
  "S4" => S4, "FRWD" => FRWD, "BKWD" => BKWD, "RRWD" => RRWD, "RLWD" => RLWD},

```

```

ImageMargins → 10, Background → LightGreen], Background → LightYellow];

cc := Framed[Row[{Button["START", {START, msg$ = msg2}, Background → Green],
  ButtonBar[{" GO " → GO, "M1" → sDmd[1, ldy], "M2" → sDmd[2, rdy] },
  ImageMargins → 5, Background → LightOrange],
  Button["REBOOT", {R, msg$ = msg3}, Background → Red]}], Background → White];

dd := Pane[ButtonBar[
  {"Forward" → F, "RotateLeft" → RL, "STOP" → S, "TurnLeft" → TL, "BackToLeft" → BTL,
  "VeerLeft" → VL, "RampUp" → RU}, ImageMargins → 5, Background → LightGreen]];

ee := Pane[ButtonBar[
  {"Backward " → B, "RotateRight" → RR, " Halt " → H, "TurnRight" → TR, "BackToRight" → TR,
  "VeerRight" → VR, "RampDown" → RD}, ImageMargins → 5, Background → LightGreen]];

ff := Grid[{{dd}, {ee}}, Frame → All, Background → LightYellow];

gg := Panel[Row[{"dt ", {Slider[Dynamic[dt], {25, 500, 5}], Dynamic[dt]},
  " n ", {Slider[Dynamic[n], {0, 50, 1}], Dynamic[n]}]],
  "Time Increment (ms) and Step No."];

hh := Panel[Row[{"Inch ", {Slider[Dynamic[in], {0, 50
  , 1}], Dynamic[in]}, " Deg ", {Slider[Dynamic[deg], {0, 180, 5}], Dynamic[deg]}]],
  "Inches and Degrees"];

ii :=
  Framed[Panel[ButtonBar[{"GODT" → GODT[dt], "STEP" → STEP[n, dt], "GF" → sDmd[6, in],
    "GB" → sDmd[7, in], "GRR" → sDmd[8, deg], "GRL" → sDmd[9, deg],
    "GTR" → sDmd[10, deg], "GTL" → sDmd[11, deg]}, ImageMargins → 5,
    Background → LightGreen, Method → "Queued"], Background → LightYellow]];

jj := Framed[
  Grid[{{Button["MAN1", {msg$ = msg4, sMan[1]}], Button["MAN2", {msg$ = msg5, sMan[2]}],
    Button["MAN3", sMan[3]}], {Button["MAN4", sMan[4]},
    Button["MAN5", sMan[5]}, Button["MAN6", sMan[6]}]], Spacings → {0, 0}},
  Background → LightYellow];

kk := Framed[
  Panel[ Row[{Button["PING", xi = sRd[1]], InputField[Dynamic[xi], FieldSize → {4, 1}],
    " ", "Degrees", Slider[Dynamic[pos], {-90, 90, 5}], Dynamic[pos],
    " ", Button["SERVO", sDmd[5, pos]], " ", Button["GamePad",
    {msg$ = msg6, nx = 1; XBOX}, Method → "Queued"]}], Background → LightYellow]];

ll := Framed[Row[
  {Button["LENC", lenc = sRd[2]}, " ", InputField[Dynamic[lenc], FieldSize → {4, 1}],
  Button["RENC", renc = sRd[3]}, " ", InputField[Dynamic[renc], FieldSize → {4, 1}],
  " ", Button["ZENC", zenc]}], Background → White];

mm := Row[{InputField[Dynamic[msg$], Appearance → "DialogBox", FieldSize → {30, 1}],
  " Time (sec): ", InputField[te, FieldSize → {3, 1}]}];

```

```

In[65]:= bx1 := ControllerState["B1"]
bx2 := ControllerState["B2"]
bx3 := ControllerState["B3"]
bx4 := ControllerState["B4"]
bx5 := ControllerState["B5"]
bx6 := ControllerState["B6"]
bx7 := ControllerState["B7"]
bx8 := ControllerState["B8"]
bx9 := ControllerState["B9"]
bx10 := ControllerState["B10"]

sx1 := ControllerState["X1"]
sy1 := ControllerState["Y1"]
sx2 := ControllerState["X2"]
sy2 := ControllerState["Y2"]
sx3 := ControllerState["X3"]
sy3 := ControllerState["Y3"]

XBOX := While[nx > 0, If[sx3 == -1, S1]; If[sx3 == 1, S3];
  If[sy3 == 1, S2]; If[sy3 == -1, S4]; If[bx1, F]; If[bx2, B]; If[bx3, RR];
  If[bx4, RL]; If[bx5, TR]; If[bx6, TL]; If[bx7, H]; If[bx8, Break[]];
  If[bx10, {ld1 = Round[sx2 * 500], rd1 = Round[sy2 * 500], sDmd[1, ld1], sDmd[2, rd1]}];
  Pause[0.2]]

In[82]:= console := Framed[
  Panel[Column[{mm, aa, bb, Row[{cc, " ", ll}], ff, gg, hh, Row[{ii, " ", jj}], kk}],
  Background → LightCyan]

```

In[83]:= **console**

" Press START to Activate Robot Control" Time (sec): 35

Speed Settings (Sx)

ldty { , 100 } rdy { , 100 }

Sx S1 S2 S3 S4 FRWD BKWD RRWD RLWD

START GO M1 M2 REBOOT LENC lenc RENC renc ZENC

Forward RotateLeft STOP TurnLeft BackToLeft VeerLeft RampUp

Backward RotateRight Halt TurnRight BackToRight VeerRight RampDown

Time Increment (ms) and Step No.

dt { , 25 } n { , 0 }

Inches and Degrees

Inch { , 0 } Deg { , 0 }

GODT STEP GF GB GRR GRL GTR GTL

MAN1	MAN2	MAN3
MAN4	MAN5	MAN6

PING xi Degrees -90 SERVO GamePad

Out[83]=